

ESD-TDR-66-158

ESD RECORD COPY

RETURN TO
SCIENTIFIC & TECHNICAL INFORMATION DIVISION
(ESTI), BUILDING 1211

ESD ACCESSIO LIST

ESTI Call No. AL 50684

Copy No. 1 of 1 cys.

Technical Note

1966-8

R. Teoste

Haystack Pointing System:
Satellite Acquisition

30 March 1966

Prepared under Electronic Systems Division Contract AF 19(628)-5167 by

Lincoln Laboratory

MASSACHUSETTS INSTITUTE OF TECHNOLOGY

Lexington, Massachusetts



ESRL

AD06 32489

The work reported in this document was performed at Lincoln Laboratory, a center for research operated by Massachusetts Institute of Technology, with the support of the U.S. Air Force under Contract AF 19(628)-5167.

This report may be reproduced to satisfy needs of U.S. Government agencies.

Distribution of this document is unlimited.

MASSACHUSETTS INSTITUTE OF TECHNOLOGY
LINCOLN LABORATORY

HAYSTACK POINTING SYSTEM: SATELLITE ACQUISITION

R. TEOSTE

Group 62

TECHNICAL NOTE 1966-8

30 MARCH 1966

LEXINGTON

MASSACHUSETTS

ABSTRACT

Haystack Pointing System consists of hardware and software which points the Haystack 120-foot X-band antenna dish with great accuracies. The Satellite Acquisition program, described in this report, generates acquisition scans and searches for target returns. Once the target has been sighted, the program tracks the target by conical scanning. After acquisition, time correction can be made in the orbit computations.

Accepted for the Air Force
Franklin C. Hudson
Chief, Lincoln Laboratory Office

HAYSTACK POINTING SYSTEM: SATELLITE ACQUISITION

INTRODUCTION

One of the objectives of the Haystack facility is to track satellites for various experiments. Monopulse autotrackers have been built for this purpose. The autotrackers require that the antenna beam be pointed at the satellite, before automatic tracking can take place. The satellite program^{1,2} of the Haystack Pointing System³ is capable of computing azimuth and elevation commands from orbit parameters; but past experience has shown that the accuracy of the available orbit parameters is too poor to place the satellite within the antenna beam. An initial search has to be conducted to locate the satellite before autotracking can take place.

An acquisition program has been written for the Univac 490 computer to facilitate a more orderly search and acquisition. The primary objective of this program is to find the target and point the antenna at it long enough for the autotracker to lock on and follow the target from the acquisition point. However, the program is capable of independently tracking the satellite by continuously sensing the discrepancy between the computed commands and the actual target position.

The program was written to be used with the first Haystack radar equipment and the sequential doppler processor built by W. F. Kelley⁴. This equipment generates a pulse, called a RP2 pulse, whenever the receiver output exceeds a given threshold. These pulses can be generated by noise and false targets as well as the target which is being tracked.

Indeed, the program only requires that a RP2 like signal be given the computer whenever the target is within the antenna beam. Hence, any equipment that generates

1. A. A. Mathiasen and J. D. Drinan, editors, "Haystack Pointing System: Satellite," Lincoln Laboratory Technical Note 1965-36, (9 September 1965).
2. A. A. Mathiasen, editor, "Haystack Pointing System: Mathematical Development for Satellites and Belts," Lincoln Laboratory Technical Note 1965-49, (23 September 1965).
3. A. A. Mathiasen and J. D. Drinan, "Haystack Pointing System: Control Structure," Lincoln Laboratory Technical Note 1966-10, (March 9, 1966).
4. H. G. Weiss, "The Haystack Experimental Facility," Lincoln Laboratory Technical Report 365, (15 September 1964).

such a pulse can be used in conjunction with the acquisition program. R. Silva has constructed a CW monopulse autotracker which generates the RP2 pulse whenever signals exceed a threshold. The acquisition program has successfully acquired one of the Lincoln experimental satellites, LES II, using this equipment.

The Haystack computer can send pointing commands to the Westford antenna over telephone lines⁵. A. Dockrey has built circuitry at the Westford site to allow a RP2 pulse to be sent back to the Haystack U-490 computer under various modes of Westford equipment operation. The acquisition program has acquired satellites by means of Westford equipment in the radar mode as well as in the CW mode.

Since the doppler and range predictions are usually within the required accuracies, the acquisition program only searches and acquires in azimuth and elevation angles. No provision has been made for range or doppler acquisition.

The program acquires in two phases. First, a search scan is generated which grossly looks for the target. It does this by superimposing a long and narrow scan along the orbit and searching for RP2 pulses. Secondly, when a hit is received (designated by an RP2 pulse), the values of azimuth and elevation for the target are observed and a local scan is initiated around these coordinates. The local scan consists of a set of concentric circles. The radius of the consecutive circles being increased by about one beamwidth from one circle to the next. The local scan is continuously computed, even after the antenna is controlled by the analog tracker; so that if at any time the analog tracker should lose the target, the computer will have a correct pointing angle already computed in the buffer region. By simply changing the antenna mode to computer pointing, the target will again be acquired.

When the program has made three successful local scans, a message is printed to indicate that the target has been acquired. At this time the operator can ask the program to compute and affect a time correction in orbit computations which is expected to correct most of the error in predicted angles. If reacquisition is later required, the acquisition program will not have to search quite as large an area. A local scan may be sufficient for reacquisition after time correction has been made.

5. J. E. Gillis, "Haystack-West Ford Intersite Coupling Link," Lincoln Laboratory Group Report 1964-25, (14 May 1964).

The program is under complete control of the operator. The automatic sequence of scans just described can be overridden by means of the keyboard. For instance, at any time the search scan can be made to start over, fixed biases can be added to the predicted commands, the program computed errors can be set to zero, only local scan can be requested if predictions are known to be sufficiently accurate, etc.

OPERATOR INTERVENTION

Figure 1 shows a typical on-line record of operator action. Typical acquisition scans are shown by Fig. 2 where the command elevation is plotted as a function of command azimuth. When the pointing system is requested to point at a satellite, the question "Do you want acquisition" is asked and three choices are given as shown in Fig. 1. The only other method of getting to the acquisition program is through the attention symbol as shown by Fig. 1. When the program is reached through the attention symbol, the operator is offered more choices.

1. Stop Acquisition

This choice stops the acquisition scans and causes the program to ignore the RP2 interrupts.

2. Search Scan

This choice sets up the normal acquisition mode. The program will first scan in a long and narrow area of uncertainty along the orbit. The scan shown in Fig. 3 is superimposed on the computed pointing commands. The length and width of the scan is requested through the keyboard. When RP2 pulses are observed, the program automatically switches to local scan. When RP2 pulses disappear for a sufficiently long period the program goes back to search scan.

3. Local Scan

This choice allows the program to superimpose only a local scan on the pointing commands. Figure 4 shows a local scan. The RP2 pulses are observed as usual.

SYSTEM DATA RECORDING...COMPLETE(0) PARTIAL(1) NONE(2) 0
*

DO YOU WANT ACQUISITION

NO(1) SEARCH SCAN(2) LOCAL SCAN(3)
2*

ENTER SCAN LENGTH IN DEGREES
3*

ENTER SCAN WIDTH IN DEGREES
.4*

DATA PROCESSING PROGRAM..
NONE(0) RADIOMETER(1) RADIOMETER SCAN(2) MERCURY EXP(3)
*
Ⓢ

SIGN OFF(1) MOD(2) NEXT RUN(3) PRINT(4)
2*

SAT (1) DATA PROCESSING(2) SCAN(3) RECORDING(4) TIMING(5) OTHER(6)
6*

RA-DEC DISPLAY(1) CORRECTION(2) PARAMETERS(3) ACQUISITION(4)
CC(5) DYDMP(6) PLOT(7) AUTOT(8)
4*

STOP (1) SEARCH(2) LOCAL(3) CL BIAS(4) SET BIAS(5) TIME (6) HS(7) WF(8)
5*

ENTER AZIMUTH BIAS IN DEGREES
5.328 *

ENTER ELEVATION BIAS IN DEGREES
3.8 *
Ⓢ

SIGN OFF(1) MOD(2) NEXT RUN(3) PRINT(4)
1*

TITLE

Fig. 1. Example of on-line printout.

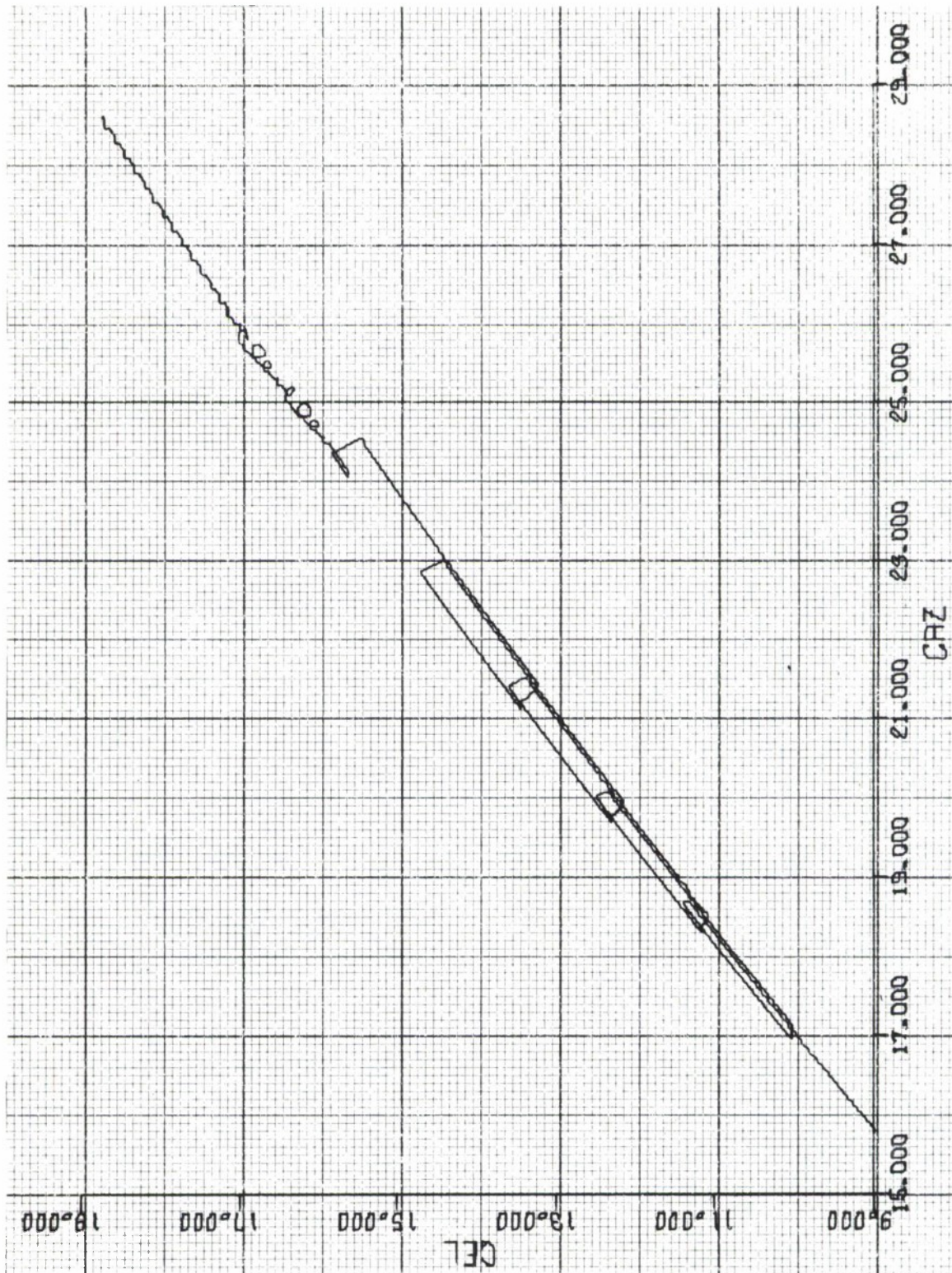


Fig. 2. Typical acquisition.

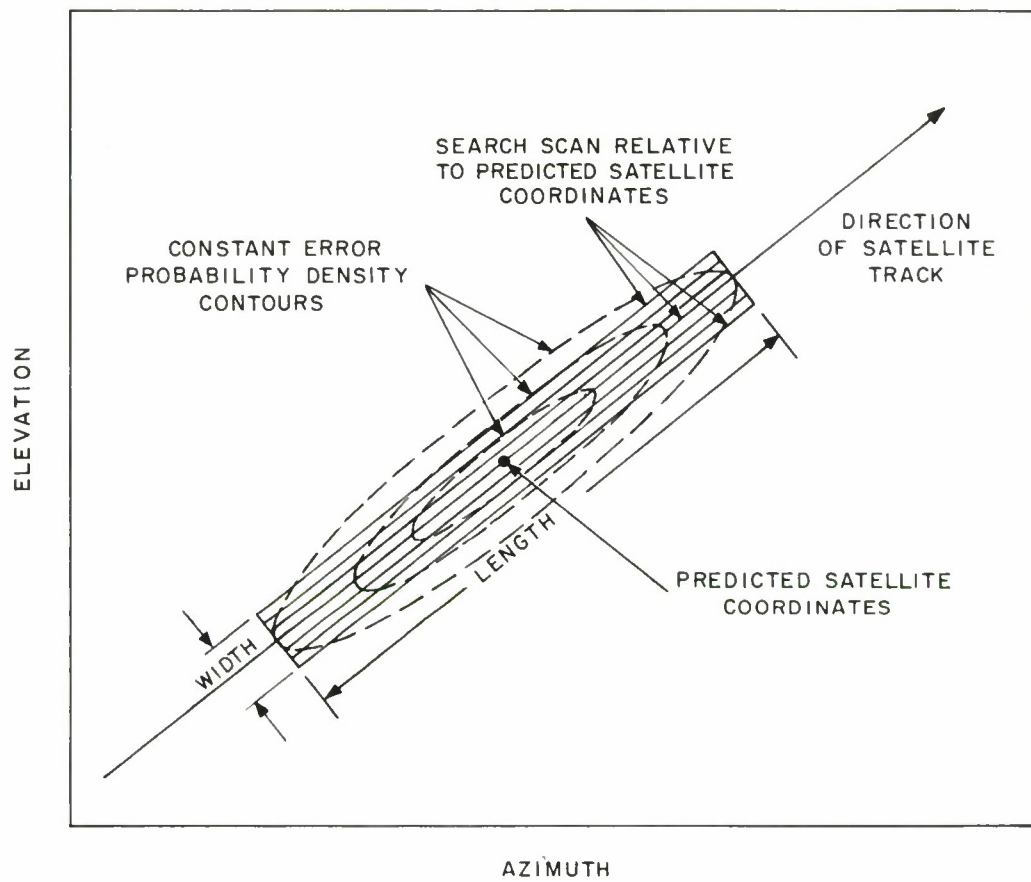


Fig. 3. Search scan.

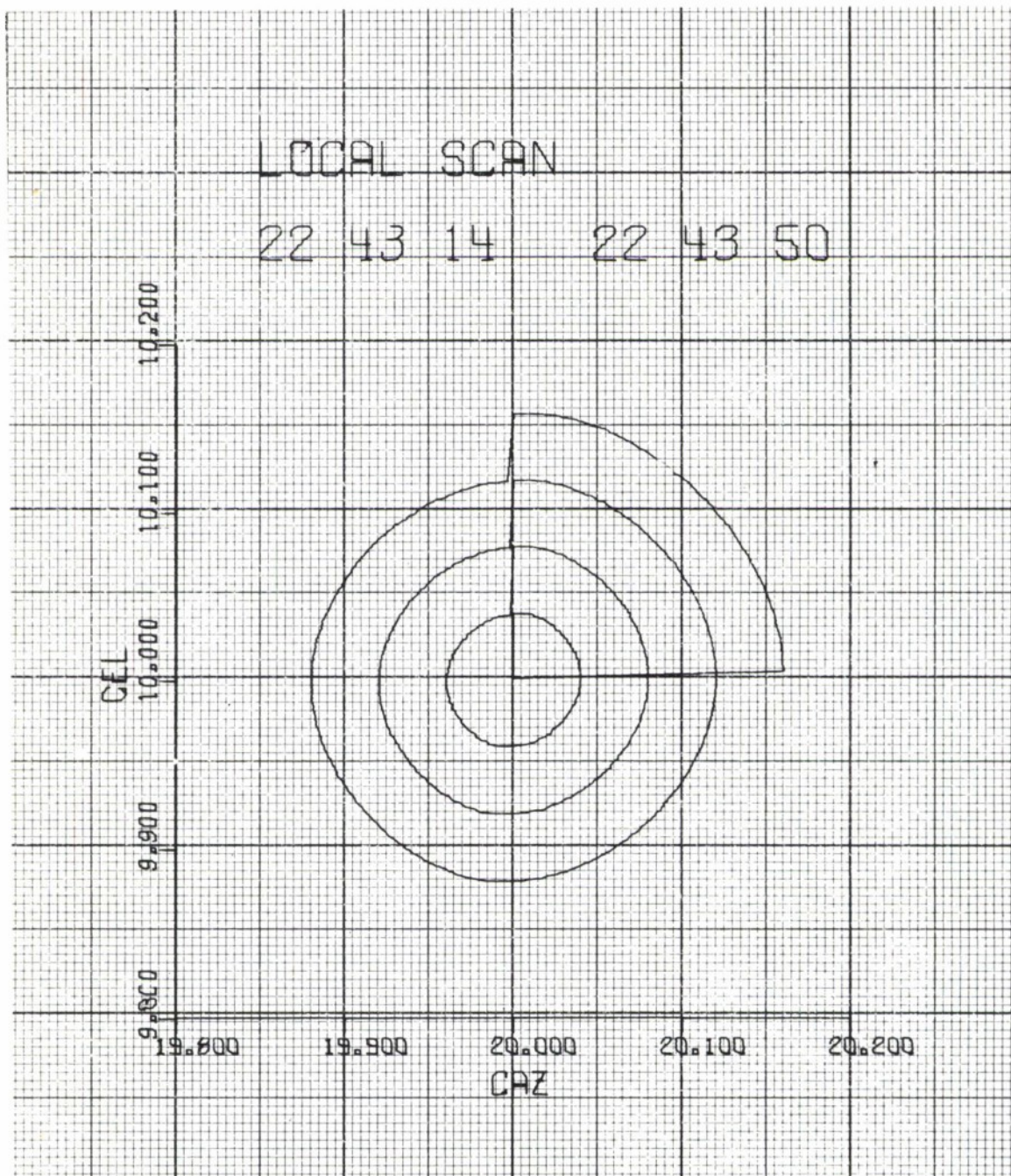


Fig. 4. Local scan.

4. Clear Biases

This choice clears the computed error biases in the local scan.

5. Set Biases

This choice sets the azimuth and elevation local scan biases to the keyboard entered values.

6. Time Correction

This choice causes a time correction to be made in the ephemeris computation, based on the errors in commands at that particular time.

7. Haystack Acquisition

This choice makes the program operate with Haystack RP2 pulses (channel 8 external interrupts). Search or local scan must be requested before the new site RP2 pulses will be used.

8. Westford Acquisition

This choice makes the program operate with Westford RP2 pulses (channel 12 external interrupts). Search or local scan must be requested before the new site RP2 pulses will be used.

PROGRAM INPUTS AND OUTPUTS

Basically the acquisition program computes four values of azimuth and elevation using predicted pointing azimuth and elevation from common storage and puts the four resulting values into common storage. However, additional inputs and outputs are used.

Core Storage Inputs

W(CAZIM):- Predicted satellite azimuth coordinate for $T_0 + 4$ seconds in revolutions B27. T_0 , $T_0 + 2$ is the two second time interval for which the next data is to be interpolated.

W(CELEV):- Predicted satellite elevation coordinate for $T_0 + 4$ seconds in revolutions B27.

W(AZIMOVER):- A code to indicate where the first azimuth point is to be placed. When AZIMOVER is positive first azimuth will be placed in the main antenna zone. When AZIMOVER is negative first azimuth will be placed in the overlap zone.

W(TIMEMODE):- A code to indicate if system is running in real time. When TIMEMODE is positive, the system is running in real time. Negative TIMEMODE indicates simulated time.

W(INAZIMADD):- INAZIMADD gives the input azimuth buffer locations. Upper half gives the first word address of presently read into buffer. Lower half gives first word address of previously read in buffer.

W(113):- Azimuth in buffer control word.

Interrupt Inputs

The program uses external interrupts on channel 8 (range channel) for Haystack gear and channel 10 (intersite coupling channel) for Westford gear.

Keyboard Inputs

The program accepts search scan length and width in degrees whenever search scan is requested. It also accepts the local scan azimuth and elevation biases when operator requests that option. Keyboard entered parameters are in degrees.

Core Storage Outputs

W(ACQAZIM), + 1, + 2, + 3:- Four values of azimuth which have acquisition commands superimposed on predicted azimuth commands. Values are in revolutions B27.

W(ACQELEV), + 1, + 2, + 3:- Four values of elevation which have acquisition commands superimposed on predicted elevation commands. Values are in revolutions B27.

W(TIMECORR):- Time correction in days B28.

W(TRACKINDIC):- A code which is set to -0 whenever RP2 pulses are observed and to +0 when no RP2 pulses are observed.

On-Line Printer Output

When a target has been acquired, a message "Target Acquired" is printed on the high-speed printer by means of the printer log program⁶.

Keyboard Outputs

Miscellaneous typing out is performed by means of INTERCOM⁷ as shown by Fig. 1.

INTERNAL OPERATION OF PROGRAM

Initially, the program is made to scan either according to the search scan or the local scan. When the target is observed, the equipment external to the U-490 computer generates a RP2 pulse which appears at the computer as an external interrupt. The interrupt answering routine collects the interrupts in a table over the two second pointing system cycle. Every two seconds, the acquisition program is entered and all of the RP2 pulses are averaged to obtain an average target position. Then the predicted position is computed for that precise instant and an error is computed. This error is added to the future predicted commands and a local scan is initiated around these new coordinates. False alarms are allowed in the sense that if during the whole local scan no RP2 pulses are received, search will be continued by returning to the scan which was previously in operation. If RP2 pulses are observed during a local scan, a new local scan will be generated with the new errors as the new center point for the scan. Thus, once the target is observed, the program will track the target by continuously making one local scan after another. When three successful local scans have been made, a message is printed on the high-speed printer and only then a request for time correction will be honored.

Search Scan

The selection of search scan has received considerable attention. Typical prediction errors show that the error along the satellite track is much greater than

-
6. J. D. Drinan (editor), "Haystack Pointing System: Auxiliary Real-Time Programs," Lincoln Laboratory Technical Note 1966-6, (31 January 1966).
 7. A. A. Mathiasen and J. D. Drinan, editors, "Haystack Pointing System: INTERCOM," Lincoln Laboratory Technical Note 1965-39, (9 September 1965).

the deviation from the track. These errors specify a long narrow area of uncertainty with the highest probability of actual target location occurring in the center and along the satellite track. Obviously, one would like to scan the highest probability area first and then proceed to the lower probability areas. Typical constant error probability density contours are shown in Fig. 3.

The search scan also depends on the equipment limitations. The antenna control characteristics are such that large pointing errors occur when the antenna is asked to follow high rates. This suggests slow scans. Also the radar pulse repetition frequency determines minimum dwell time. One would like to have the target in the antenna beam long enough to get at least one and preferably several radar returns. These considerations dictate a quite slow search procedure. With a constant acceleration scan just slow enough for the antenna servo, an area of one degree by five degrees can be scanned in about eight minutes.

The values of L (the length along trajectory) and W (the width of scan) are given to the acquisition program via the keyboard routine. A scan is generated which goes along the trajectory $L/2$ ahead of the predicted value and $L/2$ behind the predicted value, then moves almost one beamwidth ($.04^\circ$) in cross-scan direction and repeats the scan along the trajectory, then moves almost one beamwidth to the other side of the trajectory and repeats again. The lateral distance from the trajectory is increased almost one beamwidth from one along the trajectory scan to the next, until a width of $W/2$ is scanned on each side of the trajectory. If the target has not been found then, a new scan is initiated with parameters L and W increased by 50%.

It is expected that the satellite acquisition program will be used mainly on the horizon when the satellite first comes into view. The first scan simply waits on the horizon and adjusts the azimuth so that a satellite could be acquired if it is early or late in its orbit. After this first scan, the above described pattern is used.

The scan along the satellite orbit (S) is computed by using a constant acceleration scan.

$$S = 2aI[2N - |I|] \quad , \quad (1)$$

where a is the constant acceleration, I is an index which is increased or decreased every two seconds, and N is the number of two second intervals in the half scan, and is computed by first computing a time (T).

$$T = \sqrt{\frac{L}{a_{\max}}} \quad , \quad (2)$$

where L is the scan length and a_{\max} is the maximum allowable acceleration of pointing commands. N is then computed such that

$$T \leq 2N - .5 \quad . \quad (3)$$

The value of the constant scan acceleration, a , is computed by

$$a = \frac{L}{(2N)^2} \quad . \quad (4)$$

The value of a obtained by this procedure is approximately equal to a_{\max} .

From the azimuth and elevation differences performed on the previous values, the trackangle, θ , is determined by

$$\theta = \tan^{-1} \left[\frac{E_1 - E_{-1}}{A_1 - A_{-1}} \right] \quad , \quad (5)$$

where E_i are the elevation values and A_i azimuth values corresponding to time T_i , as shown in Fig. 5. $T_0, T_0 + 2$ corresponds to the time period for which the commands are to be interpolated next.

The elevation command is then computed by adding the elevation component of the scan to the elevation predicted position.

$$E_2^* = E_2 + S \sin \theta \quad , \quad (6)$$

where E_2^* is the elevation coordinate of the command with the scan added. Now a azimuth value (A_2^*) is computed so that the resulting point is constrained to fall on the satellite trajectory which is indicated on Fig. 5 as the point labeled X_2 . This is accomplished by a second order fit and extrapolation

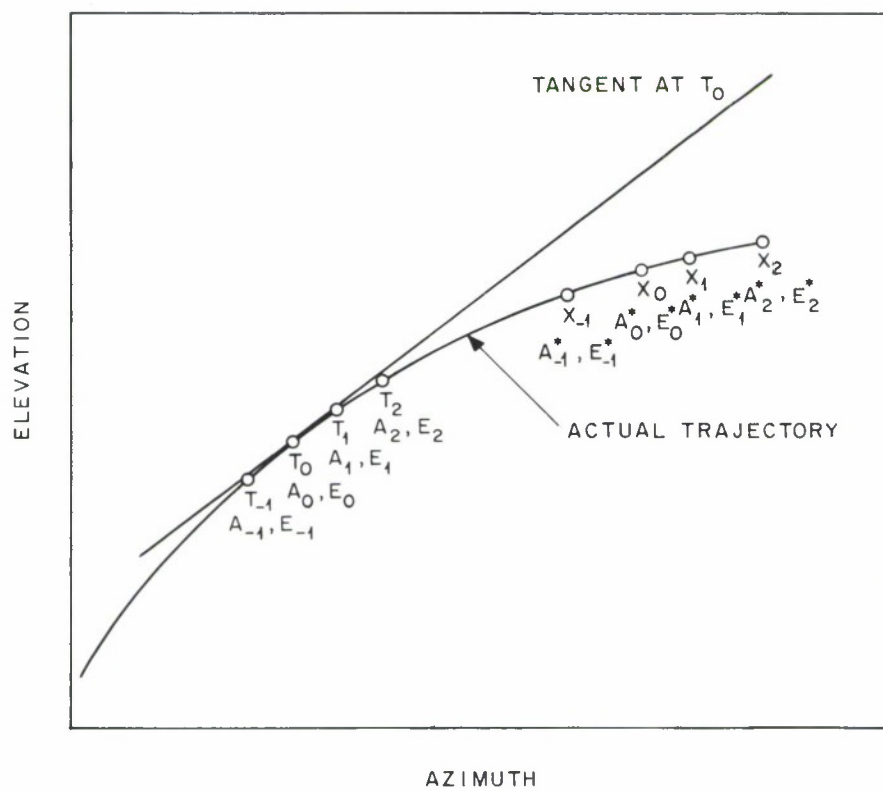


Fig. 5. Satellite trajectory.

$$A_2^* = A_2 + \frac{(A_{-1} - A_o)(E_2 - E_o)^2 - (A_2 - A_o)(E_{-1} - E_o)^2}{(E_{-1} - E_o)(E_2 - E_o)[(E_2 - E_o) - (E_{-1} - E_o)]} (E_2^* - E_o) + \frac{(A_2 - A_o)(E_{-1} - E_o) - (A_{-1} - A_o)(E_2 - E_o)}{(E_{-1} - E_o)(E_2 - E_o)[(E_2 - E_o) - (E_{-1} - E_o)]} (E_2^* - E_o)^2 \quad (7)$$

In order to prevent singularities in the computations, when $\theta < 45^\circ$, the azimuth component of the scan is computed instead by

$$A_2^* = A_2 + S \cos \theta \quad (8)$$

and the elevation is computed to fall on the curve by

$$E_2^* = E_2 + \frac{(E_{-1} - E_o)(A_2 - A_o)^2 - (E_2 - E_o)(A_{-1} - A_o)^2}{(A_{-1} - A_o)(A_2 - A_o)[(A_2 - A_o) - (A_{-1} - A_o)]} (A_2^* - A_o) + \frac{(E_2 - E_o)(A_{-1} - A_o) - (E_{-1} - E_o)(A_2 - A_o)}{(A_{-1} - A_o)(A_2 - A_o)[(A_2 - A_o) - (A_{-1} - A_o)]} (A_2^* - A_o)^2 \quad (9)$$

When the elevation is on the horizon, the minimum elevation is used as E_2^* and A_2^* is computed by Eq. (7).

The cross-scan is added to the commands by adding the components of the cross-scan to the azimuth and elevation commands.

$$\Delta C_A = \Delta C \sin \theta \quad (10)$$

and

$$\Delta C_E = \Delta C \cos \theta \quad (11)$$

where ΔC is the incremental increase in cross-scan from one scan to the next and ΔC_A and ΔC_E are the two corresponding increments, in the azimuth and elevation directions respectively.

Local Scan

The local scan configuration is not very critical and does not have to be computed very accurately, since the scan itself has very small dimensions. The local scan which was chosen first points at the center point of the scan for six seconds. Six seconds allows the antenna to move into the local scan region and allows all transients to be decreased to negligible values. Three circular scans are then performed around the center point. Each circle is made in eight seconds, and has a radius which increases almost one beamwidth ($.04^\circ$) from one circle to the next. The velocity in the smallest circle is such that the target will be observed approximately 1.25 seconds, which allows 25 hits when the pulse rate is 20 a second. The second and third circles will allow 12 and 8 hits respectively. Since the scan is relative to the predicted target position and moves along in the expected trajectory, the errors should be so small that the larger circular scans are never used. This occurs because, whenever hits are received during a local scan, the local scan is restarted with the scan center at the coordinates where hits were received.

The circular scans are computed in a novel way. The antenna commands are interpolated from four values of azimuth and elevation by means of the interpolation program⁸. The four values given to the interpolation program are such that a smooth circle is interpolated between the points. The following values of azimuth and elevation are given at the time when new points are to be interpolated between T_0 and $T_0 + 2$.

| | A_{-1} | E_{-1} | A_0 | E_0 | A_1 | E_1 | A_2 | E_2 |
|--------------|----------|----------|-------|-------|-------|-------|-------|-------|
| 1st quadrant | -R | -R | 0 | R | R | 0 | -R | -R |
| 2nd quadrant | -R | R | R | 0 | 0 | -R | -R | R |
| 3rd quadrant | R | R | 0 | -R | -R | 0 | R | R |
| 4th quadrant | R | -R | -R | 0 | 0 | R | R | -R |

The value of azimuth and elevation at T_0 are A_0 and E_0 respectively, and R is the radius of the scan at the time of computation.

8. R. Teoste, "Haystack Pointing System: Interpolation," MIT Lincoln Laboratory Group Report 1964-57, (28 October 1964).

Average Error Computation

When RP2 interrupts occur, an interrupt answering routine stores the pertinent information in a table, one interrupt at a time. During the two second cycle the acquisition program analyses the information in these tables. Each interrupt has four words of information as follows:

1. Azimuth input buffer control word
2. Range command
3. Doppler command
4. Azimuth input buffer control word

In addition, there is a table of weights which indicates the likelihood of the RP2 being a true target. Presently the table of weights consists of equal weights, because the hardware does not provide measured doppler and range information.

Every two seconds when the pointing system cycles through the acquisition program, the interrupt tables are examined and an average buffer control word $(BCW)_{avg}$ is computed for the previous two second interval by

$$(BCW)_{avg} = \frac{1}{N} \sum_{i=1}^N W_i (BCW)_i \quad (12)$$

where N RP2 pulses had been observed and W_i and $(BCW)_i$ were the weights and the buffer control words of the individual table entries. The average buffer control word is rounded to the nearest integer, and the antenna azimuth and elevation angles which correspond to this average buffer control word are read.

Predicted azimuth and elevation angles are also computed for that instant of time. Bessel's four point interpolation formula is used for this purpose which is similar to the one used in the interpolation program. The azimuth is given by

$$A(y) = \sum_{i=-1}^2 \sum_{j=0}^3 C_{ij} y^j A_i \quad (13)$$

and

$$E(y) = \sum_{i=-1}^2 \sum_{j=0}^3 C_{ij} y^j E_i \quad (14)$$

where $A(y)$ is the value of azimuth interpolated for the time shift y (in fractions of 2 seconds) as indicated by the average buffer control word. The values of C_{ij} are a direct result of the Bessel interpolation coefficients⁹. A_i are the values of azimuth with A_0 corresponding to the predicted command given at the beginning of the two second interval for which $A(y)$ is to be interpolated. $E(y)$ and E_i have the same meanings for the elevation commands.

Now the error can be computed which would have occurred, had the predicted commands been given. This is simply obtained by subtracting the interpolated predicted commands $A(y)$ and $E(y)$ from the actual values of antenna azimuth and elevation as indicated by the average buffer control word and the input angles.

In the case of the search scan, this average error over two seconds is added to the predicted commands and a local scan is generated around these coordinates. However, when RP2 pulses are observed during a local scan, the program is allowed to finish the circle and then an average error is computed for the whole circular scan. This way the antenna corrections are made in the proper direction.

Time Correction

If the operator decides that the desired target has been sighted, the program can be signaled to make a time correction in the orbit computations.

The time correction is made by computing two time increments,

$$\Delta t_1 = \frac{6}{E_2 - E_{-1}} [E_r - E_c] \quad \text{and} \quad (15)$$

$$\Delta t_2 = \frac{6}{A_2 - A_{-1}} [A_r - A_c] \quad , \quad (16)$$

9. D. R. Hartree, "Numerical Analysis," Oxford University Press, London, 1955, p. 68.

where E_p and A_p are the antenna pointing angles at the time of time correction and E_c and A_c are the predicted target coordinates at the same time. $A_p - A_c$ and $E_p - E_c$ are actually the averaged pointing corrections computed previously for locating the local scan.

Weighting elevation time correction by $\frac{E_2 - E_{-1}}{E_2 - E_{-1} + A_2 - A_{-1}}$ and azimuth time correction by $\frac{A_2 - A_{-1}}{E_2 - E_{-1} + A_2 - A_{-1}}$, we get

$$\Delta t = \frac{6(E_p - E_c + A_p - A_c)}{E_2 - E_{-1} + A_2 - A_{-1}}, \quad (17)$$

where Δt is the desired time correction. The azimuth and elevation biases that remain will be computed by

$$\Delta A = A_p - A_c - (A_2 - A_{-1}) \frac{\Delta t}{6} \quad (18)$$

and

$$\Delta E = E_p - E_c - (E_2 - E_{-1}) \frac{\Delta t}{6} \quad (19)$$

Since the new azimuth and elevation corrections ΔA and ΔE are approximate, it may take a local scan to again precisely point the antenna at the target.

PROGRAM DETAILS

The acquisition program has three entries: working entry, initialization entry and interrupt entry. The working section is entered every two seconds in the pointing system cycle, the initialization section is entered at the beginning of a run or when requested through the attention symbol, and the interrupt answering routine is entered whenever a RP2 interrupt occurs. Figures 6, 7, and 8 show the working, initialization, and interrupt section flow diagrams respectively. The flow diagrams, in conjunction with the program listing in the APPENDIX, are self explanatory.

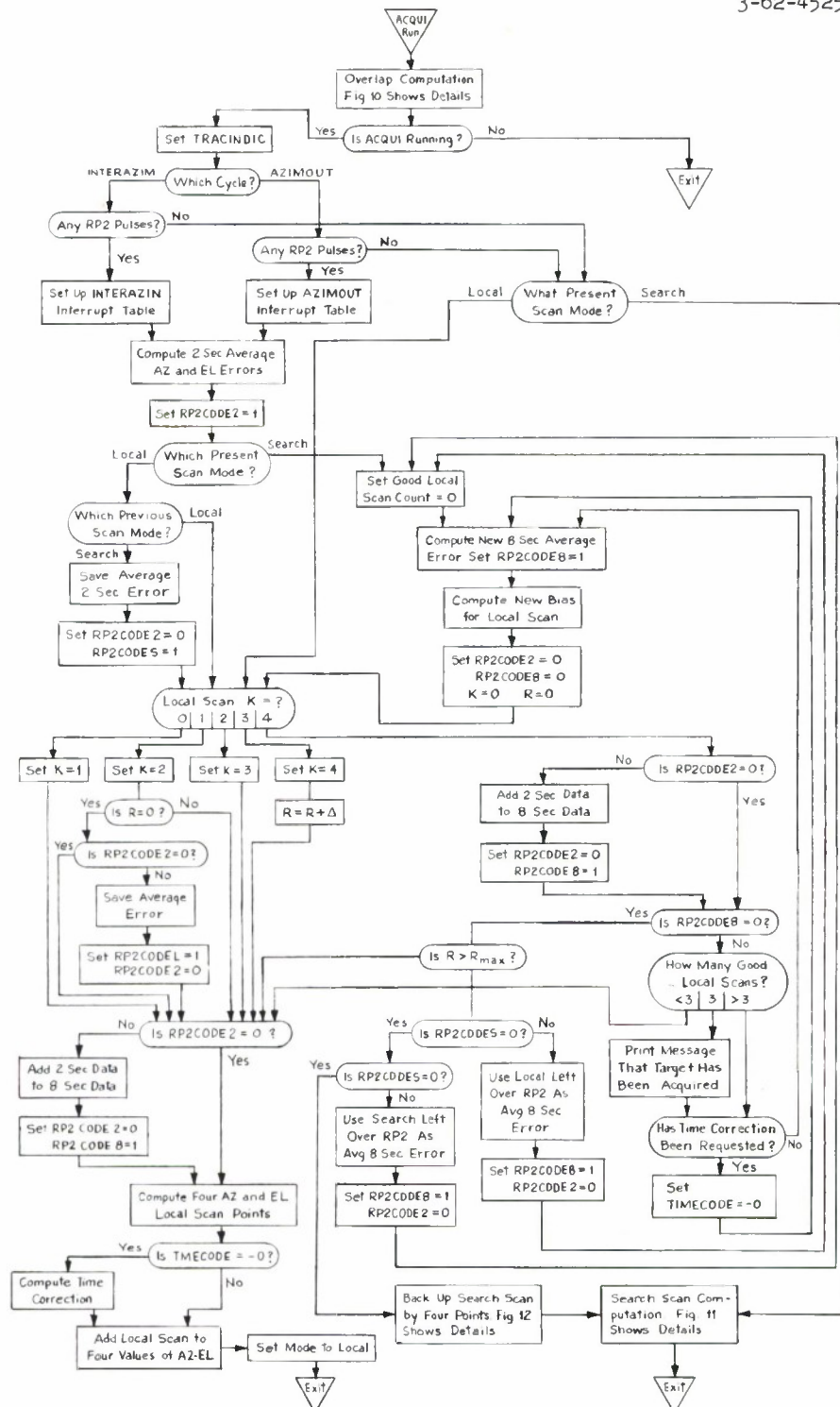


Fig. 6. Acquisition working section flow diagram.

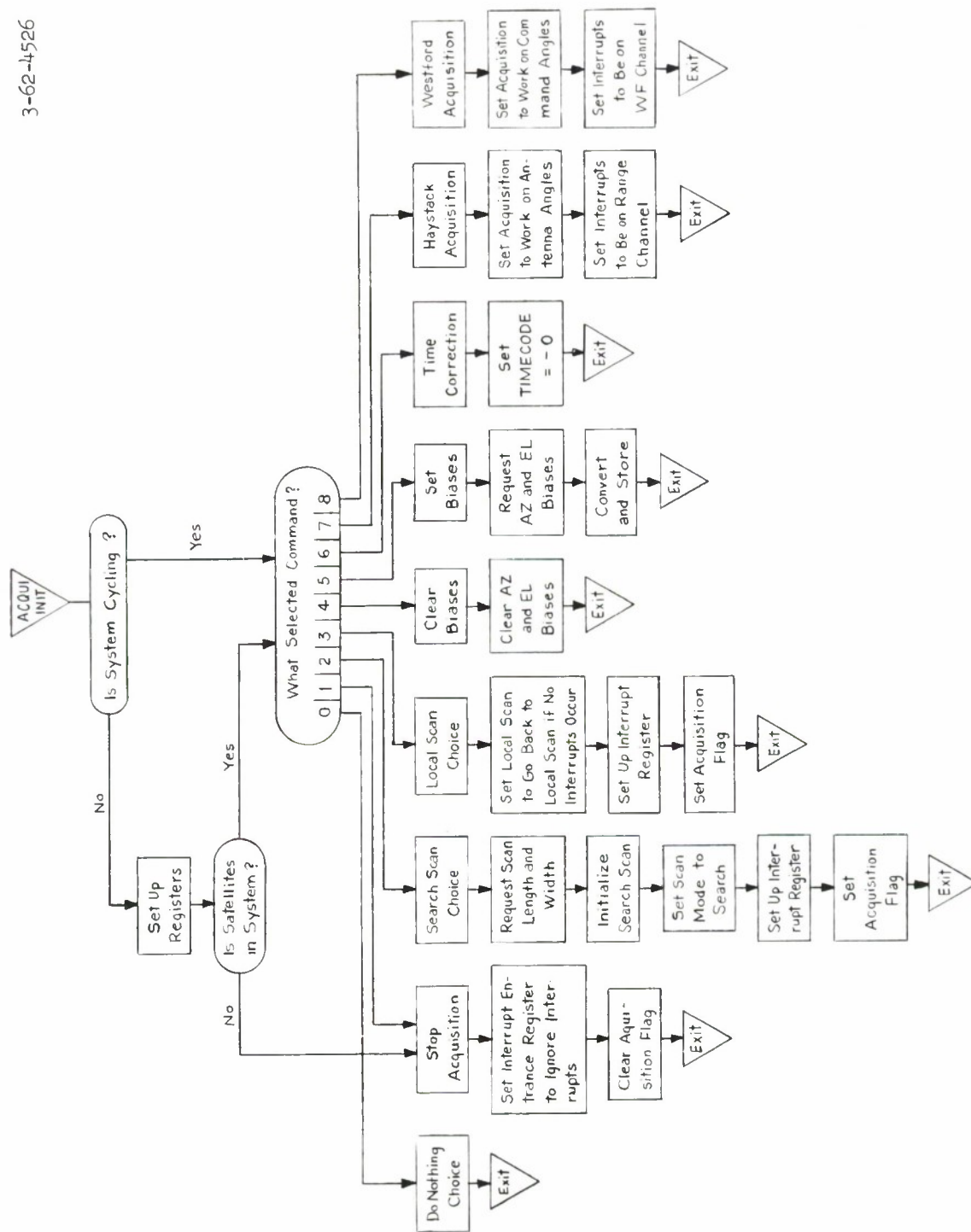


Fig. 7. Acquisition program initialization flow diagram.

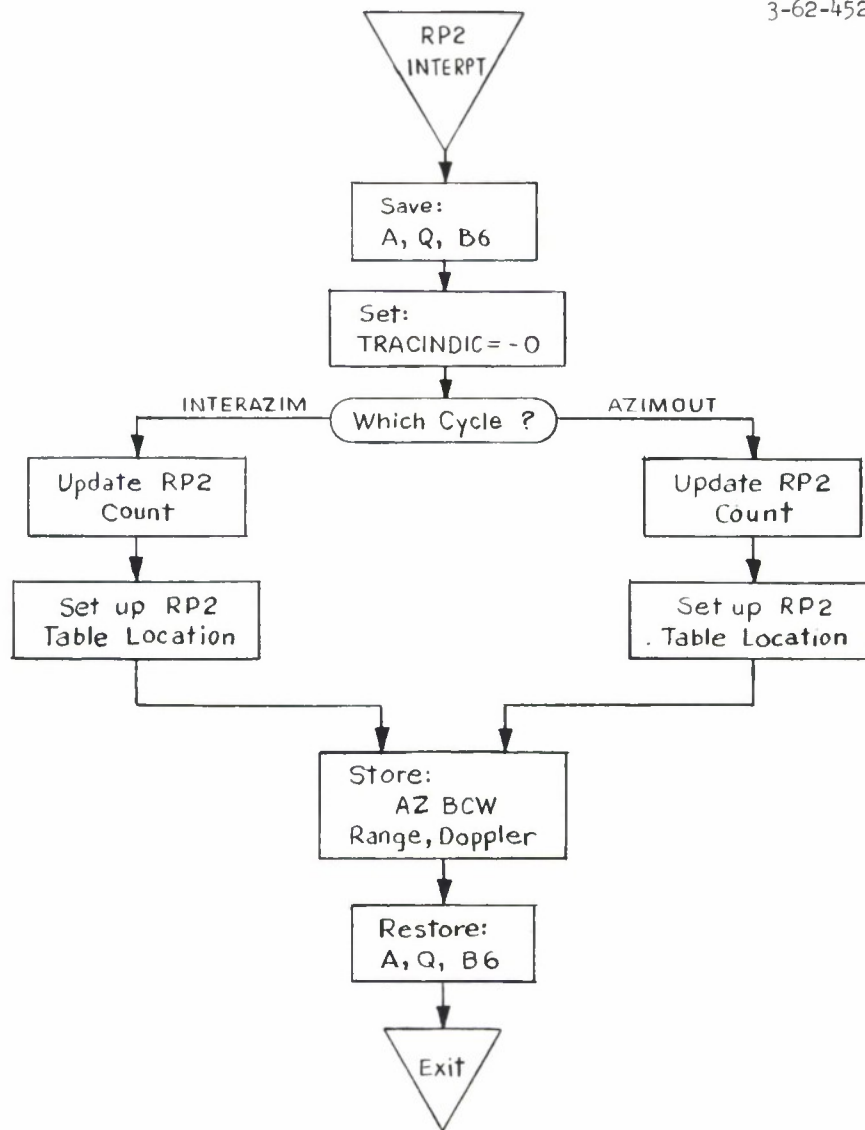


Fig. 8. Interrupt answering routine.

The initialization section performs a variety of functions. Each function is a direct result of the keyboard request, which are explained in the OPERATOR INTERVENTION section.

The interrupt answering routine serves the function of recording information when RP2 interrupts occur. This routine is entered either by the Westford RP2 interrupts or the Haystack RP2 interrupts as requested by the operator. The interrupt answering routine also sets the TRACKINDIC which is the location of a code to indicate that the target is within the antenna beam, and is used by the autotracking program.

The working section of the program contains most of acquisition program. When acquisition has not been requested, most of this program is bypassed. The values of azimuth and elevation are corrected for overlap purposes and are passed on to the interpolation program.

The Haystack antenna is capable of travelling 600 degrees in the azimuth plane. Figure 9 shows the azimuth travel limits and labels the overlap zones. The azimuth angles given the acquisition program are always between 0 and 360 degrees. The acquisition program computes the overlap information so that the antenna goes smoothly through north. The detailed computations are outlined by Fig. 10.

When the acquisition program has been asked to function, after several tests, the program computes either a local scan or a search scan. The local scan computation is broken into five alternative computations (five values of k), one for each of the four quadrants plus an additional one that is used when the local scan is reinitiated ($k = 0$ case). $k = 4$ is the first quadrant computation; during this time the previous circle is examined for RP2 pulses and appropriate computations are made when some RP2 pulses have occurred.

Figure 11 shows the search scan computations logic, while Fig. 12 shows the logic when the search scan has to be backed up four points so that continuity is preserved when after a false target the search scan is continued.

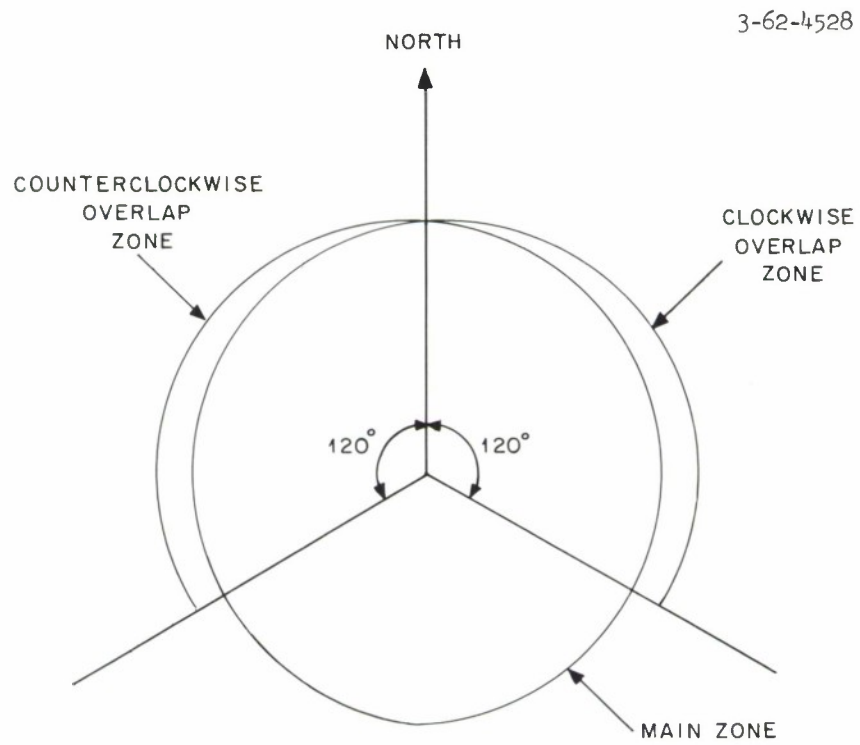


Fig. 9. Overlap zones.

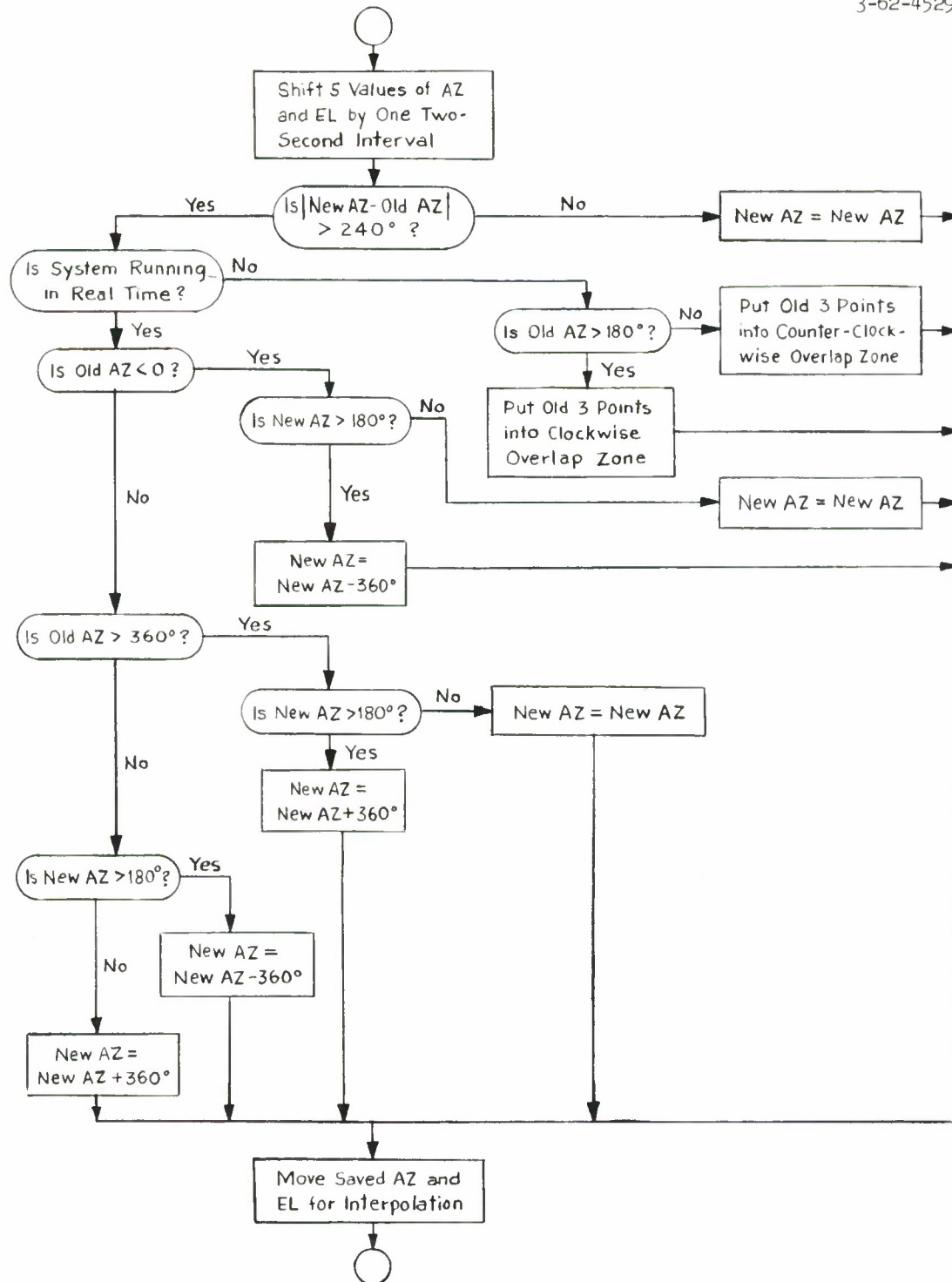


Fig. 10. Overlap computation.

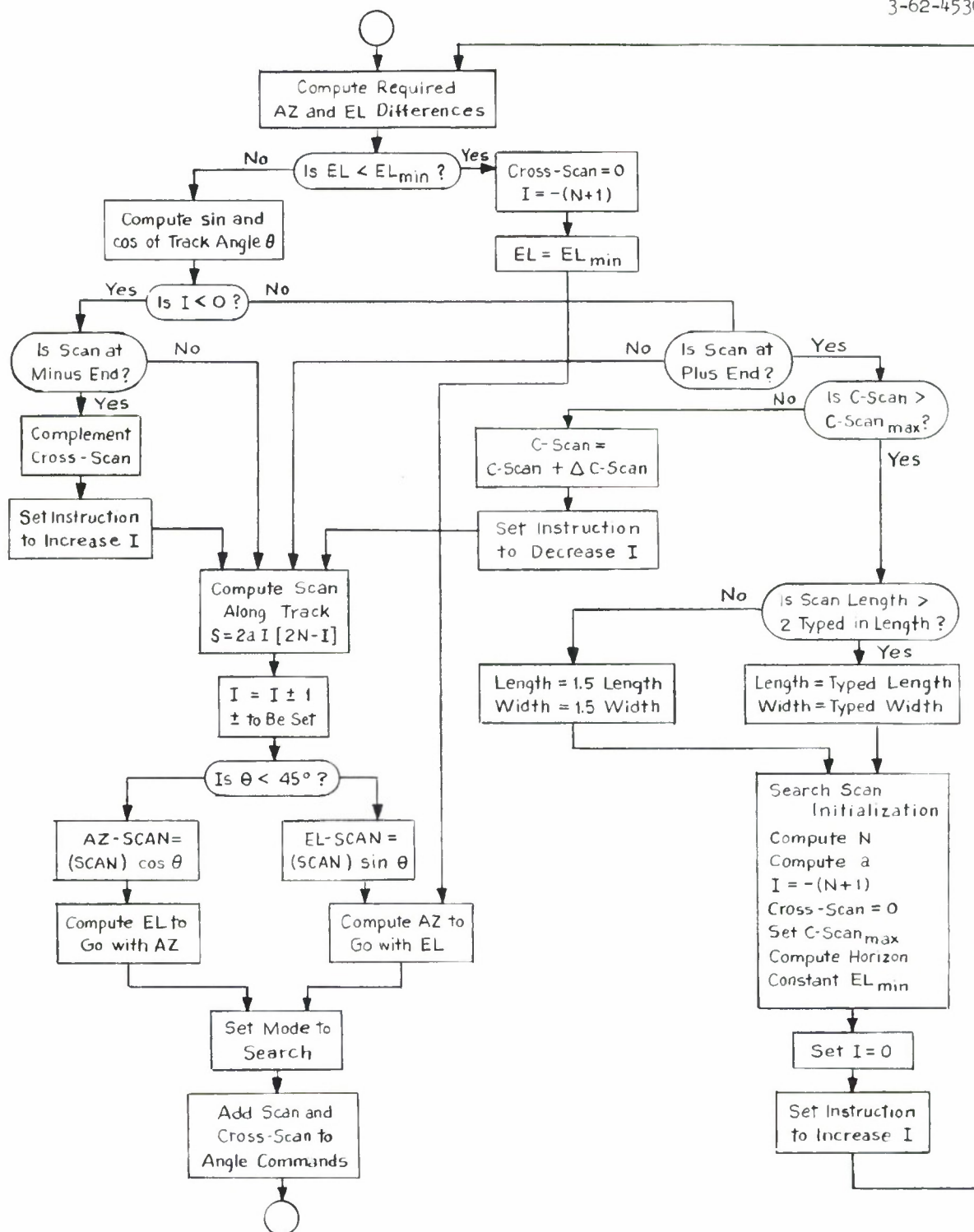


Fig. 11. Search scan computation.

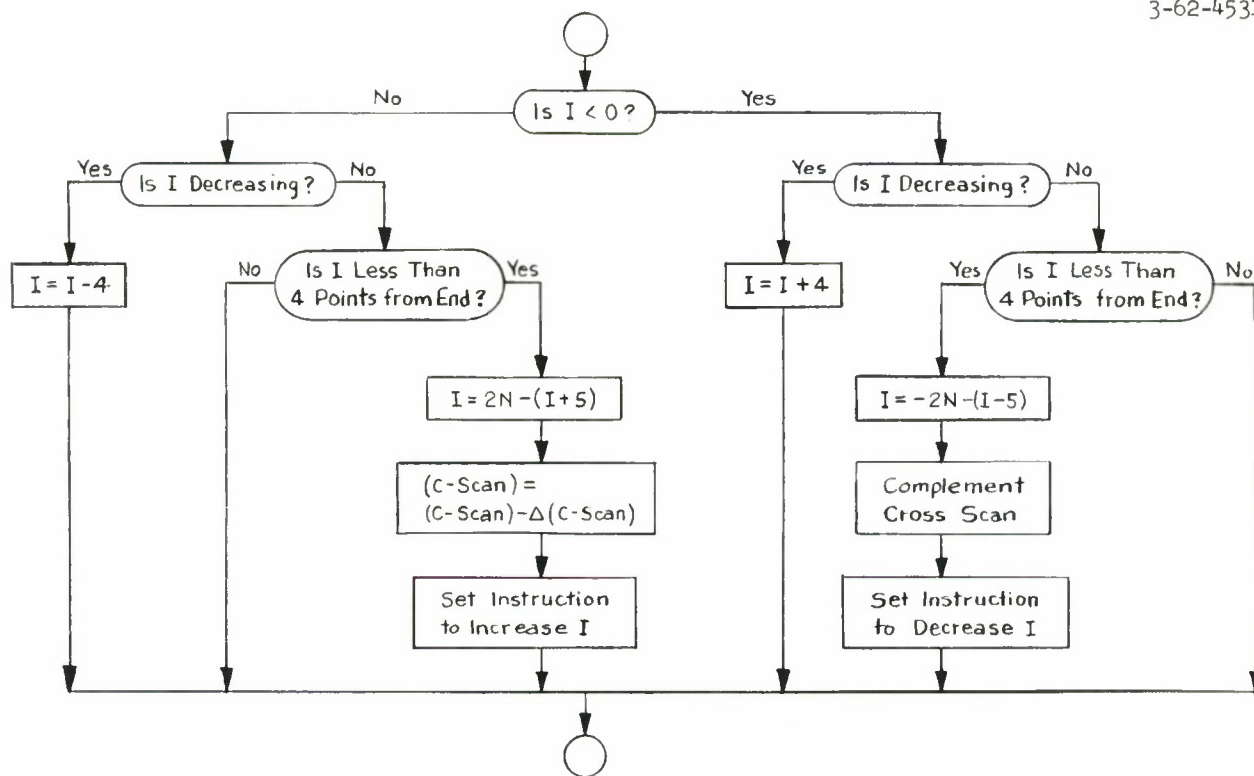


Fig. 12. Back up search scan.

APPENDIX: PROGRAM LISTING

| CARDS | L1 ID LABEL | TA STATEMENT | LOC | F | JKB | Y | NOTES |
|-------|------------------|--------------------------|-------|-------|-------|---|---------------------------------------|
| | | PROGRAM TEOSTE*10FEB66 | | | | | |
| | 00000 ACQUI | U-TAG ACQUIRUN*ACQUIINIT | 00000 | 00360 | 00002 | | |
| | 00001 ACQUIRE | FD 1*ACQUI | 00001 | 06102 | 63216 | | |
| | 00002 | ENTRY | 00002 | 61000 | 00000 | | |
| | 00003 ACQUIINIT | ENT A*XL(SYSTAT1)*ANEG | 00003 | 11750 | 63313 | | IS SYSTEM CYCLING |
| | 00004 | JP ATTENTINIT | 00004 | 61000 | 00034 | | |
| | 00005 | CL W(AZENTBIAS) | 00005 | 16030 | 00272 | | |
| | 00006 | CL W(ELENTBIAS) | 00006 | 16030 | 00273 | | |
| | 00007 | CL W(TIMECODE) | 00007 | 16030 | 00217 | | |
| | 00010 | PUT 1*L(CHOICE) | 00010 | 10000 | 00001 | | |
| | 00011 | | 00011 | 14010 | 00040 | | |
| | 00012 | ENT A*(TEST3) | 00012 | 11030 | 00344 | | |
| | 00013 | STR A*(STARTAZ) | 00013 | 15030 | 00370 | | |
| | 00014 | CL W(RP2CODE2) | 00014 | 16030 | 01215 | | U(LOCAL SCAN K) L(RP2CODE2) |
| | 00015 | CL W(RP2CODE8) | 00015 | 16030 | 01216 | | U(END LOC SCAN) L(RP2CODE8) |
| | 00016 | CL W(RP2CODES) | 00016 | 16030 | 01217 | | L(RP2CODES) U(N0 OF GOOD LOCAL SCANS) |
| | 00017 | CL W(RP2COUNT) | 00017 | 16030 | 02573 | | |
| | 00020 | CL L(RP2CODEL) | 00020 | 16010 | 01220 | | L(RP2CODEL) |
| | 00021 | CL W(RP2AVG8E) | 00021 | 16030 | 01231 | | |
| | 00022 | CL W(RP2AVG8A) | 00022 | 16030 | 01212 | | |
| | 00023 | ENT A*L(SYSTAT2) | 00023 | 11010 | 63314 | | IS SATELLITES IN SYSTEM |
| | 00024 | SUB A*2*AZERO | 00024 | 21400 | 00002 | | NO |
| | 00025 | JP STOPACQUI | 00025 | 61000 | 00042 | | YES |
| | 00026 | RJP U(INTERCOM) | 00026 | 65020 | 63426 | | DO YOU WANT ACQUISITION |
| | 00027 | U-TAG QUEST1*0 | 00027 | 00060 | 00000 | | |
| | 00030 | RJP U(INTERCOM) | 00030 | 65020 | 63426 | | N0(1) SEARCH SCAN(2) LOCAL S |
| | 00031 | U-TAG QUEST3*ANSWER1 | 00031 | 00105 | 00070 | | CAN(3) |
| | 00032 | ENT B7*L(CHOICE) | 00032 | 12710 | 00040 | | |
| | 00033 | JP L(PROGTABLE+B7) | 00033 | 61017 | 00074 | | JUMP TO THE REQUESTED PROGRAM |
| | 00034 ATTENTINIT | RJP U(INTERCOM) | 00034 | 65020 | 63426 | | ATTENTION INITIALIZATION |
| | 00035 | U-TAG QUEST2*ANSWER2 | 00035 | 00120 | 00142 | | |
| | 00036 | ENT B7*L(CHOICE) | 00036 | 12710 | 00040 | | |
| | 00037 | JP L(PROGTABLE+B7) | 00037 | 61017 | 00074 | | JUMP TO THE REQUESTED PROGRAM |
| | 00040 CHOICE | 1 | 00040 | 00000 | 00001 | | |
| | 00041 DO NOTHING | JP L(ACQUIINIT) | 00041 | 61010 | 00002 | | |
| | 00042 STOPACQUI | ENT A*(S+1)*SKIP | 00042 | 11130 | 00043 | | SKIP ALL OF ACQUI |
| | 00043 | RJP NOINTERR | 00043 | 65000 | 00052 | | |
| | 00044 | STR A*(30) | 00044 | 15030 | 00030 | | |
| | 00045 | STR A*(34) | 00045 | 15030 | 00034 | | |
| | 00046 | CL W(ACQUIONOFF) | 00046 | 16030 | 00057 | | |
| | 00047 | PUT -0*(TRACKINDIC) | 00047 | 10040 | 77777 | | |
| | 00050 | JP L(ACQUIINIT) | 00050 | 14030 | 63026 | | |
| | 00051 NOINTERR | ENTRY | 00051 | 61010 | 00002 | | |
| | 00052 | PUT -0*(TRACKINDIC) | 00052 | 61000 | 00000 | | SET TRACK INDIC. WHEN NOT ACQUIRING |
| | 00053 | | 00053 | 10040 | 77777 | | |
| | 00054 | STR C14*(RP2CHANNEL) | 00054 | 14030 | 63026 | | |
| | 00055 | | 00055 | 17630 | 02575 | | |

| | | | | | | | |
|-------|------------|-------------------|--|------------|-------|-------|--------------------------|
| 00054 | ACQUIONOFF | RILJP | L(NOINTERR) | 00056 | 60110 | 00052 | |
| 00055 | QUEST1 | 0 | | 00057 | 00000 | 00000 | |
| 00056 | | FD | 0*A | 00060 | 06000 | 00000 | |
| 00057 | | -0 | \$+1 | 00061 | 77777 | 00062 | |
| 00060 | | FD | 0*00 YOU WANT ACQUISITION | 00062 | 11240 | 53624 | |
| | | | | 00063 | 32053 | 40623 | |
| | | | | 00064 | 31050 | 61026 | |
| | | | | 00065 | 32163 | 01631 | |
| | | | | 00066 | 16242 | 30000 | |
| | | | | 00067 | 77777 | 77777 | |
| 00061 | ANSWER1 | -0 | | 00070 | 11000 | 00000 | |
| 00062 | | FD | 0*D | 00071 | 00011 | 00040 | |
| 00063 | | 11 | CHOICE | 00072 | 00000 | 00001 | |
| 00064 | | 1 | | 00073 | 00000 | 00003 | |
| 00065 | PROGTABLE | 3 | | 00074 | 00000 | 00041 | DO NOTHING (0) |
| 00066 | | 0 | DONOTHING | 00075 | 00000 | 00042 | STOP SCAN (1) |
| 00067 | | 0 | STOPACQUI | 00076 | 00000 | 00163 | SEARCH SCAN (2) |
| 00070 | | 0 | SCHCHOICE | 00077 | 00000 | 00330 | LOCAL SCAN (3) |
| 00071 | | 0 | LOCCHOICE | 0100 | 00000 | 00210 | CLEAR BIASES (4) |
| 00072 | | 0 | CLBIASES | 0101 | 00000 | 00252 | SET BIASES (5) |
| 00073 | | 0 | SETBIASES | 0102 | 00000 | 00214 | TIME CORRECTION (6) |
| 00074 | | 0 | TIMECORREC | 0103 | 00000 | 00146 | HAYSTACK ACQUISITION (7) |
| 00075 | | 0 | HSACQUI | 0104 | 00000 | 00156 | WESTFORD ACQUISITION (8) |
| 00076 | | 0 | WFACQUI | 0105 | 06000 | 00000 | |
| 00077 | QUEST3 | FD | 0*A | 0106 | 77777 | 00107 | |
| 00100 | | -0 | \$+1 | 0107 | 23245 | 16140 | |
| 00101 | | FD | 0*NO(1) | LOCAL SCAN | 00107 | | |
| | | (3) | | | | | |
| | | | | 0110 | 05053 | 01206 | |
| | | | | 0111 | 27101 | 50530 | |
| | | | | 0112 | 10062 | 35162 | |
| | | | | 0113 | 40050 | 52124 | |
| | | | | 0114 | 10062 | 10530 | |
| | | | | 0115 | 10062 | 35163 | |
| | | | | 0116 | 40000 | 00000 | |
| 00102 | QUEST2 | -0 | | 0117 | 77777 | 77777 | |
| 00103 | | FD | 0*A | 0120 | 06000 | 00000 | |
| 00104 | | -0 | \$+1 | 0121 | 77777 | 00122 | |
| 00105 | | FD | 0*STOP (1) SEARCH(2) LOCAL(3) CL BI00122 | 0122 | 30312 | 42505 | |
| | | AS(4) SET BIAS(5) | | | | | |
| | | | | 0123 | 51614 | 00530 | |
| | | | | 0124 | 12062 | 71015 | |
| | | | | 0125 | 51624 | 00521 | |
| | | | | 0126 | 24100 | 62151 | |
| | | | | 0127 | 63400 | 51021 | |
| | | | | 0130 | 05071 | 60630 | |
| | | | | 0131 | 51644 | 00530 | |
| | | | | 0132 | 12310 | 50716 | |
| | | | | 0133 | 06305 | 16540 | |
| | | | | 0134 | 05311 | 62212 | |
| | | | | 0135 | 05516 | 64005 | |
| | | | | 0136 | 15305 | 16740 | |
| | | | | 0137 | 05341 | 35170 | |
| | | | | 0140 | 40000 | 00000 | |
| | | | | 0141 | 77777 | 77777 | |
| 00106 | | FD | 0* TIME (6) HS(7) WF(8) | 0142 | 11000 | 00000 | |
| | | | | 0143 | 00011 | 00040 | |
| | | | | 0144 | 00000 | 00001 | |
| | | | | 0145 | 00000 | 00011 | |
| | | | | 0146 | 11000 | 63446 | |
| 00107 | ANSWER2 | -0 | | | | | |
| 00110 | | FD | 0*D | | | | |
| 00111 | | 11 | CHOICE | | | | |
| 00112 | | 1 | | | | | |
| 00113 | | 11 | | | | | |
| 00114 | HSACQUI | ENT | A*INAZIMADD | | | | |

SET UP ACQUI FOR HAYSTACK

| | | | | | |
|-------|------------|--------------------------------|-------|-------|-------|
| 00115 | ENT | Q*30 | 00147 | 10000 | 00030 |
| 00116 | ENT | B6*INELEVADO | 00150 | 12600 | 63447 |
| 00117 | STR | A*L(WFHSACQUI1) | 00151 | 15010 | 01432 |
| 00120 | STR | B6*L(WFHSACQUI2) | 00152 | 16610 | 01445 |
| 00121 | STR | Q*L(WFHSACQUI4+1) | 00153 | 14010 | 00206 |
| 00122 | STR | Q*L(WFHSACQUI5+1) | 00154 | 14010 | 00337 |
| 00123 | JP | L(ACQUIINIT) | 00155 | 61010 | 00002 |
| 00124 | ENT | A*AZIMADD | 00156 | 11000 | 63442 |
| 00125 | ENT | Q*34 | 00157 | 10000 | 00034 |
| 00126 | ENT | B6*ELEVADO | 00160 | 12600 | 63443 |
| 00127 | JP | WFHSACQUI6 | 00161 | 61000 | 00151 |
| 00130 | ENT | A*W(1)*AP0S | 00162 | 11630 | 00561 |
| 00131 | RJP | U(INTERCOM) | 00163 | 65020 | 63426 |
| 00132 | U-TAG | QUEST4*ANSWER4 | 00164 | 00220 | 00231 |
| 00133 | RJP | U(INTERCOM) | 00165 | 65020 | 63426 |
| 00134 | U-TAG | QUEST5*ANSWERS | 00166 | 00235 | 00246 |
| 00135 | PUT | W(LENGTHIN)*W(LENGTH) | 00167 | 10030 | 00745 |
| 00136 | PUT | W(WIDTHIN)*W(WIDTH) | 00171 | 10030 | 00744 |
| 00137 | CL | W(RP2COUNT) | 00172 | 14030 | 01205 |
| 00140 | RJP | SSCANINIT | 00173 | 16030 | 02573 |
| 00141 | ENT | Q*W(BACKUPWD) | 00174 | 65000 | 01134 |
| 00142 | ENT | A*1 | 00175 | 10030 | 00162 |
| 00143 | SIL | A*(SCANMODE) | 00177 | 11000 | 00001 |
| 00144 | STR | A*(SCANMODE) | 00200 | 64000 | 00000 |
| 00145 | STR | Q*W(BACKUPSCAN) | 00200 | 15020 | 00576 |
| 00146 | STR | -0*W(ACQUIONOFF) | 00201 | 15010 | 00576 |
| 00147 | PUT | W(RP2INTRJP)*W(30) | 00202 | 14030 | 01633 |
| 00150 | RILJP | L(ACQUIINIT) | 00203 | 10040 | 77777 |
| 00151 | SIL | W(LOCSCABIAS) | 00204 | 14030 | 00057 |
| 00152 | CL | W(LOCSCABIAS) | 00205 | 10030 | 00343 |
| 00153 | CL | W(LOCSCABIAS) | 00206 | 14030 | 00030 |
| 00154 | RILJP | L(ACQUIINIT) | 00207 | 60110 | 00002 |
| 00155 | PUT | -0*U(TIMECODE) | 00210 | 64000 | 00000 |
| 00156 | JP | L(ACQUIINIT) | 00211 | 16030 | 01225 |
| 00157 | 0 | | 00212 | 16030 | 01227 |
| 00160 | FD | 0*A | 00213 | 60110 | 00002 |
| 00161 | FD | 0*A | 00214 | 10040 | 77777 |
| 00162 | FD | 0*ENTER SCAN LENGTH IN DEGREES | 00215 | 14020 | 00217 |
| 00163 | FD | 0*ENTER SCAN LENGTH IN DEGREES | 00216 | 61010 | 00002 |
| 00164 | -0 | 0*X18 | 00217 | 00000 | 00000 |
| 00165 | FD | 11 LENGTHIN | 00220 | 06000 | 00000 |
| 00166 | 0 | 0 | 00221 | 77777 | 00222 |
| 00167 | 0024000000 | | 00222 | 12233 | 11227 |
| 00170 | FD | 0*A | 00223 | 05301 | 00623 |
| 00171 | QUEST5 | | 00224 | 05211 | 22314 |
| 00172 | -0 | \$+1 | 00225 | 31150 | 51623 |
| 00173 | FD | 0*ENTER SCAN WIDTH IN DEGREES | 00226 | 05111 | 21427 |
| | | | 00227 | 12123 | 00000 |
| | | | 00230 | 77777 | 77777 |
| | | | 00231 | 35617 | 00000 |
| | | | 00232 | 00011 | 00745 |
| | | | 00233 | 00000 | 00000 |
| | | | 00234 | 00240 | 00000 |
| | | | 00235 | 06000 | 00000 |
| | | | 00236 | 77777 | 00237 |
| | | | 00237 | 12233 | 11227 |
| | | | 00240 | 05301 | 00623 |
| | | | 00241 | 05341 | 61131 |

ENTER SCAN LENGTH IN DEGREES

ENTER SCAN WIDTH IN DEGREES

MAKE SCAN BACK UP
SET SCAN MODE TO SEARCH

20B18 MAXIMUM SCAN LENGTH

| | | | | | | | | | |
|---|-------|-----------|------------|-----------------------------------|-------|-------|-------|-------|--------------------------------|
| • | 00174 | ANSWERS | -0 | FD | 0*X18 | 00242 | 15051 | 62305 | |
| • | 00175 | | 11 | WIDTHIN | | 00243 | 11121 | 42712 | |
| • | 00176 | | 0 | | | 00244 | 12300 | 00000 | |
| • | 00177 | | 0 | | | 00245 | 77777 | 77777 | |
| • | 00200 | | 0005000000 | | | 00246 | 35617 | 00000 | |
| • | 00201 | SETBIASES | RJP | U(INTERCOM) | | 00247 | 00011 | 00744 | |
| • | 00202 | | U-TAG | QUEST6*ANSWER6 | | 00250 | 00000 | 00000 | |
| • | 00203 | | RJP | U(INTERCOM) | | 00251 | 00050 | 00000 | |
| | | | | | | 00252 | 65020 | 63426 | SB18 MAXIMUM SCAN WIDTH |
| | | | | | | 00253 | 00275 | 00306 | ENTER AZIMUTH BIAS IN DEGREES |
| | | | | | | 00254 | 65020 | 63426 | ENTER ELEVATION BIAS IN DEGREE |
| • | 00204 | | U-TAG | QUEST7*ANSWER7 | | 00255 | 00312 | 00324 | S |
| • | 00205 | | ENT | Q*W(AZENTBIAS) | | 00256 | 10030 | 00272 | CONVERT AZ BIAS TO REVOLUTIONS |
| • | 00206 | | MUL | W(RECIPREV) | | 00257 | 22030 | 01202 | |
| • | 00207 | | LSH | AQ*9D | | 00260 | 07000 | 00011 | |
| • | 00210 | | STR | A*(TEMPST) | | 00261 | 15030 | 00274 | |
| • | 00211 | | ENT | Q*W(ELENTBIAS) | | 00262 | 10030 | 00273 | CONVERT EL BIAS TO REVOLUTION |
| • | 00212 | | MUL | W(RECIPREV) | | 00263 | 22030 | 01202 | |
| • | 00213 | | LSH | AQ*9D | | 00264 | 07000 | 00011 | |
| • | 00214 | | ENT | Q*W(TEMPST) | | 00265 | 10030 | 00274 | |
| • | 00215 | | SIL | | | 00266 | 64000 | 00000 | CHANGE BIASES |
| • | 00216 | | STR | A*(LOCSCABIAS) | | 00267 | 15030 | 01227 | |
| • | 00217 | | STR | Q*(LOCSCABIAS) | | 00270 | 14030 | 01225 | |
| • | 00220 | | RILJP | L(ACQUINIT) | | 00271 | 60110 | 00002 | |
| • | 00221 | AZENTBIAS | 0 | | | 00272 | 00000 | 00000 | B18 KEYBOARD ENTERED AZ BIAS |
| • | 00222 | ELENTBIAS | 0 | | | 00273 | 00000 | 00000 | B18 KEYBOARD ENTERED EL BIAS |
| • | 00223 | TEMPST | 0 | | | 00274 | 00000 | 00000 | |
| • | 00224 | QUEST6 | FD | 0*A | | 00275 | 06000 | 00000 | |
| • | 00225 | | -0 | \$+1 | | 00276 | 77777 | 00277 | |
| • | 00226 | | FD | 0*ENTER AZIMUTH BIAS IN DEGREES | | 00277 | 12233 | 11227 | |
| | | | | | | 00300 | 05063 | 71622 | |
| | | | | | | 00301 | 32311 | 50507 | |
| | | | | | | 00302 | 16063 | 00516 | |
| | | | | | | 00303 | 23051 | 11214 | |
| | | | | | | 00304 | 27121 | 23000 | |
| | | | | | | 00305 | 77777 | 77777 | |
| • | 00227 | ANSWER6 | -0 | FD | 0*X18 | 00306 | 35617 | 00000 | |
| • | 00230 | | 11 | AZENTBIAS | | 00307 | 00011 | 00272 | |
| • | 00231 | | 7227777777 | | | 00310 | 72277 | 77777 | -360B18 |
| • | 00232 | | 0550000000 | | | 00311 | 05500 | 00000 | 360B18 |
| • | 00233 | QUEST7 | FD | 0*A | | 00312 | 06000 | 00000 | |
| • | 00234 | | -0 | \$+1 | | 00313 | 77777 | 00314 | |
| • | 00235 | | FD | 0*ENTER ELEVATION BIAS IN DEGREES | | 00314 | 12233 | 11227 | |
| • | 00236 | | | | | 00315 | 05122 | 11233 | |
| | | | | | | 00316 | 06311 | 62423 | |
| | | | | | | 00317 | 05071 | 60630 | |
| | | | | | | 00320 | 05162 | 30511 | |
| | | | | | | 00321 | 12142 | 71212 | |
| | | | | | | 00322 | 30000 | 00000 | |
| | | | | | | 00323 | 77777 | 77777 | |
| | | | | | | 00324 | 35617 | 00000 | |
| • | 00237 | ANSWER7 | -0 | FD | 0*X18 | 00325 | 00011 | 00273 | |
| • | 00240 | | 11 | ELENTBIAS | | 00326 | 76457 | 77777 | -90B18 |
| • | 00241 | | 7645777777 | | | 00327 | 01320 | 00000 | 90B18 |
| • | 00242 | | 0132000000 | | | | | | |
| • | 00243 | | | | | | | | |

| | | | | | | | | |
|---|-------|------------|-------|---------------------|-------|-------|-------|---------------------------------------|
| • | 00244 | LOCCHOICE | ENT | A*(LOCSCONLY) | 00330 | 11030 | 00342 | PREVENT SCAN FROM GOING TO SFA RCH |
| • | 00245 | | CL | W(RP2COUNT) | 00331 | 16030 | 02573 | |
| • | 00246 | | SIL | | 00332 | 64000 | 00000 | |
| • | 00247 | | STR | A*(BACKUPSCAN) | 00333 | 15030 | 01633 | |
| • | 00250 | | PUT | -0*(ACQUIONOFF) | 00334 | 10040 | 77777 | |
| • | 00251 | WFHSACQUI5 | PUT | W(RP2INTRJP)*W(30) | 00335 | 14030 | 00057 | |
| • | 00252 | | CL | W(SCANMODE) | 00336 | 10030 | 00343 | SET MODE TO LOCAL |
| • | 00253 | | RILJP | L(ACQUINIT) | 00337 | 14030 | 00030 | |
| • | 00254 | LOCSCONLY | JP | INITLOCSC | 00340 | 16030 | 00576 | |
| • | 00255 | RP2INTRJP | RJP | RP2INTERPT | 00341 | 60110 | 00002 | |
| • | 00256 | TEST3 | JP | S+1 | 00342 | 61000 | 01563 | |
| • | 00257 | | ENT | A*(TEST4) | 00343 | 65000 | 02577 | |
| • | 00260 | | STR | A*(STARTAZ) | 00344 | 61000 | 00345 | FIRST TIME THROUGH FIX OVERLAP |
| • | 00261 | | ENT | A*(AZIMOVER)*ANEG | 00345 | 11030 | 00357 | |
| • | 00262 | | JP | ENDAZ-1 | 00346 | 15030 | 00370 | |
| • | 00263 | TEST5 | ENT | G*(CAZIM) | 00347 | 11730 | 63325 | |
| • | 00264 | | LSH | AQ*3 | 00350 | 61000 | 00402 | PUT POINT IN OVERLAP REGION |
| • | 00265 | | ENT | A*(CAZIM)*QPOS | 00351 | 10030 | 63060 | |
| • | 00266 | | SUB | A*(REV)*SKIP | 00352 | 07000 | 00003 | |
| • | 00267 | | ADD | A*(REV) | 00353 | 11230 | 63060 | |
| • | 00270 | | JP | ENDAZ | 00354 | 21130 | 00466 | |
| • | 00271 | TEST4 | JP | ENDAZ | 00355 | 20030 | 00466 | |
| • | 00272 | ACQUIRUN | ENT | 127000000 | 00356 | 61000 | 00403 | |
| • | 00273 | | CL | B7 | 00357 | 01270 | 00000 | |
| • | 00274 | | ENT | A*(ELEVSH+1+B7) | 00360 | 61000 | 00000 | |
| • | 00275 | | STR | A*(ELEVSH+B7) | 00361 | 12700 | 00000 | |
| • | 00276 | | BSK | B7*4 | 00362 | 11037 | 00477 | |
| • | 00277 | | JP | S-3 | 00363 | 15037 | 00476 | |
| • | 00300 | | ENT | A*(CELEV) | 00364 | 71700 | 00004 | NEW ELEVATION |
| • | 00301 | | STR | A*(ELEVSH+5) | 00365 | 61000 | 00362 | |
| • | 00302 | STARTAZ | CL | B7 | 00366 | 11030 | 63061 | |
| • | 00303 | | ENT | A*(AZIMSH+1+B7) | 00367 | 15030 | 00503 | |
| • | 00304 | | STR | A*(AZIMSH+B7) | 00370 | 12700 | 00000 | |
| • | 00305 | | BSK | B7*4 | 00371 | 11037 | 00471 | |
| • | 00306 | | JP | S-3 | 00372 | 15037 | 00470 | |
| • | 00307 | | ENT | A*(AZIMSH+4) | 00373 | 71700 | 00004 | |
| • | 00310 | | SUB | A*(CAZIM)*APDS | 00374 | 61000 | 00371 | NEW AZIMUTH OVERLAP DETERMINAT ION |
| • | 00311 | | STR | A*A | 00375 | 11030 | 00474 | |
| • | 00312 | | SUB | A*(MARGIN)*ANEG | 00376 | 21630 | 63060 | |
| • | 00313 | | JP | TEST1 | 00377 | 15040 | 00000 | |
| • | 00314 | | ENT | A*(CAZIM) | 00400 | 21730 | 00467 | |
| • | 00315 | ENDAZ | STR | A*(AZIMSH+5) | 00401 | 61000 | 00444 | POINT IN NONOVERLAP REGION |
| • | 00316 | | ENT | A*(ELEVSH+5) | 00402 | 11030 | 63060 | |
| • | 00317 | | STR | A*(ACGELEV+3) | 00403 | 15030 | 00475 | |
| • | 00320 | | ENT | A*(AZIMSH+5) | 00404 | 11030 | 00503 | |
| • | 00321 | | STR | A*(ACGAZIM+3) | 00405 | 15030 | 63100 | |
| • | 00322 | | ENT | A*(ACQUIONOFF)*ANOT | 00406 | 11030 | 00475 | |
| • | 00323 | | JP | L(ACQUIRUN) | 00407 | 15030 | 63074 | |
| • | 00324 | | ENT | A*(RP2COUNT)*ANOT | 00410 | 11530 | 00057 | |
| • | 00325 | | CL | W(TRACKINDIC) | 00411 | 61010 | 00360 | |
| • | 00326 | | ENT | A*(INAZIMADO) | 00412 | 11530 | 02573 | |
| • | 00327 | | SUB | A*(AZIMIN*AZERO | 00413 | 16030 | 63026 | |
| • | 00330 | | JP | INTERAZCY | 00414 | 11020 | 63446 | WHICH PREVIOUS CYCLE |
| • | 00331 | | ENT | A*(RP2COUNT)*AZERO | 00415 | 21400 | 75000 | |
| • | | | | | 00416 | 61000 | 01277 | AZIMOUT CYCLE ANY RP2 PULSES |
| • | | | | | 00417 | 11420 | 02573 | |

| | | | | | | | |
|-------|----------|-----|---------------|-------|-------|-------|--------------------------------------|
| 00507 | AZPOINT | 0 | | 00575 | 00000 | 00000 | N B27 AZIMUTH COMPONENT OF SCAN |
| 00510 | SCANMODE | -1 | RESERVE 3 | 00576 | 77777 | 77776 | |
| 00511 | JUNK | 0 | | 00577 | 00000 | 00000 | B36 DEN OF FIT EXPRESSION |
| 00512 | FITDENOM | 0 | | 00602 | 00000 | 00000 | B24 QUADRATIC COEFFICIENT |
| 00513 | FITQUAD | 0 | | 00603 | 00000 | 00000 | B21 LINEAR COEFFICIENT |
| 00514 | FITLIN | 0 | | 00604 | 00000 | 00000 | |
| 00515 | SC5 | ENT | G*(SCANPOINT) | 00605 | 10030 | 00563 | |
| 00516 | | MUL | W(SCC05) | 00606 | 22030 | 00557 | |
| 00517 | | LSH | AG*2 | 00607 | 07000 | 00002 | |
| 00520 | | STR | A*(AZPOINT) | 00610 | 15030 | 00575 | B27 AZIMUTH SCAN |
| 00521 | | ENT | G*(AZDIF20) | 00611 | 10030 | 00566 | |
| 00522 | | SUB | G*(AZDIFM10) | 00612 | 27030 | 00585 | |
| 00523 | | MUL | W(AZDIF20) | 00613 | 22030 | 00566 | |
| 00524 | | RSH | AG*180 | 00614 | 03000 | 00022 | |
| 00525 | | MUL | W(AZDIFM10) | 00615 | 22030 | 00565 | |
| 00526 | | LSH | AG*120*ANOT | 00616 | 07500 | 00014 | |
| 00527 | | JP | ENDFIT+1 | 00617 | 61000 | 01117 | B45 DEN OF QUADRATIC EXPR. |
| 00530 | | STR | A*(FITDENOM) | 00620 | 15030 | 00602 | |
| 00531 | | ENT | G*(ELDIFM10) | 00621 | 10030 | 00567 | |
| 00532 | | MUL | W(AZDIF20) | 00622 | 22030 | 00566 | |
| 00533 | | LSH | AG*120 | 00623 | 07000 | 00014 | |
| 00534 | | STR | A*(JUNK) | 00624 | 15030 | 00577 | B36 |
| 00535 | | ENT | G*(ELDIF20) | 00625 | 10030 | 00570 | |
| 00536 | | MUL | W(AZDIFM10) | 00626 | 22030 | 00565 | |
| 00537 | | LSH | AG*120 | 00627 | 07000 | 00014 | |
| 00540 | | STR | A*(JUNK+1) | 00630 | 15030 | 00600 | B36 |
| 00541 | | SUB | A*(JUNK) | 00631 | 21030 | 00577 | |
| 00542 | | RSH | AG*3 | 00632 | 03000 | 00003 | |
| 00543 | | DIV | W(FITDENOM) | 00633 | 23030 | 00602 | |
| 00544 | | STR | G*(FITQUAD) | 00634 | 14030 | 00603 | B18 QUADRATIC COEFFICIENT |
| 00545 | | ENT | G*(JUNK+1) | 00635 | 10030 | 00600 | |
| 00546 | | MUL | W(AZDIFM10) | 00636 | 22030 | 00565 | |
| 00547 | | LSH | AG*120 | 00637 | 07000 | 00014 | |
| 00550 | | STR | A*(JUNK+1) | 00640 | 15030 | 00600 | B45 |
| 00551 | | ENT | G*(JUNK) | 00641 | 10030 | 00577 | |
| 00552 | | MUL | W(AZDIF20) | 00642 | 22030 | 00566 | |
| 00553 | | LSH | AG*120 | 00643 | 07000 | 00014 | |
| 00554 | | SUB | A*(JUNK+1) | 00644 | 21030 | 00600 | B45 |
| 00555 | | RSH | AG*150 | 00645 | 03000 | 00017 | |
| 00556 | | DIV | W(FITDENOM) | 00646 | 23030 | 00602 | |
| 00557 | | STR | G*(FITLIN) | 00647 | 14030 | 00604 | B15 LINEAR COEFFICIENT |
| 00560 | | ENT | G*(FITQUAD) | 00650 | 10030 | 00603 | |
| 00561 | | MUL | W(AZPOINT) | 00651 | 22030 | 00575 | B15 |
| 00562 | | ADD | A*(FITLIN) | 00652 | 20030 | 00604 | |
| 00563 | | ENT | G*A | 00653 | 10070 | 00000 | |
| 00564 | | MUL | W(AZPOINT) | 00654 | 22030 | 00575 | B12 |
| 00565 | | LSH | AG*150 | 00655 | 07000 | 00017 | |
| 00566 | | STR | A*(ELPOINT) | 00656 | 15030 | 00574 | ELEVATION TO GO WITH AZIMUTH B 27 |
| 00567 | | JP | ENDFIT+1 | 00657 | 61000 | 01117 | |
| 00570 | SC3 | ENT | A*(ECROSSCAN) | 00660 | 11030 | 00553 | CHANGE POLARITY OF CROSSCAN |
| 00571 | | STR | A*A | 00661 | 15040 | 00000 | |
| 00572 | | STR | A*(ECROSSCAN) | 00662 | 15030 | 00553 | |
| 00573 | | ENT | A*(ACROSSCAN) | 00663 | 11030 | 00554 | |
| 00574 | | STR | A*A | 00664 | 15040 | 00000 | |
| 00575 | | STR | A*(ACROSSCAN) | 00665 | 15030 | 00554 | |

| | | | | | | |
|-------|----------|---------------------|-------|-------|-------|--------------------------------|
| 00576 | ENT | A*36030 | 00666 | 11000 | 36030 | CHANGE DIRECTION OF I |
| 00577 | STR | A*U(SC10) | 00667 | 15020 | 01036 | |
| 00600 | RPL | Y+1*W(I) | 00670 | 36030 | 00561 | |
| 00601 | JP | SC1 | 00671 | 61000 | 01027 | |
| 00602 | SUB | A*W(N)*AP05 | 00672 | 21630 | 00562 | |
| 00603 | JP | SC1 | 00673 | 61000 | 01027 | |
| 00604 | ENT | A*W(CROSSCAN) | 00674 | 11030 | 00552 | |
| 00605 | SUB | A*W(CRSCW)*ANEG | 00675 | 21730 | 00560 | |
| 00606 | JP | ENDSSC | 00676 | 61000 | 00716 | |
| 00607 | ENT | Q*W(CROSSCAN) | 00677 | 10030 | 00552 | |
| 00610 | ADD | Q*W(DELCRSC) | 00700 | 26030 | 00555 | |
| 00611 | STR | Q*W(CROSSCAN) | 00701 | 14030 | 00552 | NEW VALUE OF CROSSCAN |
| 00612 | MUL | W(SCSIN) | 00702 | 22030 | 00556 | |
| 00613 | LSH | AG*2 | 00703 | 07000 | 00002 | |
| 00614 | STR | A*A | 00704 | 15040 | 00000 | |
| 00615 | STR | A*W(ACROSSCAN) | 00705 | 15030 | 00554 | AZIMUTH COMPONENT |
| 00616 | ENT | Q*W(CROSSCAN) | 00706 | 10030 | 00552 | |
| 00617 | MUL | W(SCC05) | 00707 | 22030 | 00557 | |
| 00620 | LSH | AG*2 | 00710 | 07000 | 00002 | |
| 00621 | STR | A*W(ECROSSCAN) | 00711 | 15030 | 00553 | ELEVATION COMPONENT |
| 00622 | ENT | A*37030 | 00712 | 11000 | 37030 | CHANGE DIRECTION OF I |
| 00623 | STR | A*U(SC10) | 00713 | 15020 | 01036 | |
| 00624 | RPL | Y-1*W(I) | 00714 | 37030 | 00561 | |
| 00625 | JP | SC1 | 00715 | 61000 | 01027 | |
| 00626 | ENT | A*W(LENGTH) | 00716 | 11030 | 01204 | IS L FOUR TIMES THE ORIGINAL L |
| 00627 | RSH | AG*2 | 00717 | 03000 | 00002 | |
| 00630 | SUB | A*W(LENGTH)*AP05 | 00720 | 21630 | 00745 | |
| 00631 | JP | ENDSSC1 | 00721 | 61000 | 00733 | START SCAN OVER |
| 00632 | PUT | W(LENGTH)*W(LENGTH) | 00722 | 10030 | 00745 | |
| 00633 | PUT | W(WIDTH)*W(WIDTH) | 00723 | 14030 | 01204 | |
| 00634 | RJP | SSCANINIT | 00724 | 10030 | 00744 | INITIALIZE SEARCHSCAN |
| 00635 | CL | W(I) | 00725 | 14030 | 01205 | |
| 00636 | ENT | B7*37030 | 00726 | 65000 | 01134 | |
| 00637 | STR | B7*U(SC10) | 00727 | 16030 | 00561 | |
| 00640 | JP | SEARCHSCAN+1 | 00730 | 12700 | 37030 | |
| 00641 | ENDSSC1 | ENT A*W(LENGTH) | 00731 | 16720 | 01036 | |
| 00642 | RSH | A*1 | 00732 | 61000 | 00762 | INCREASE LENGTH BY .5 |
| 00643 | ADD | A*W(LENGTH) | 00733 | 11030 | 01204 | |
| 00644 | STR | A*W(LENGTH) | 00734 | 02000 | 00001 | |
| 00645 | ENT | A*W(WIDTH) | 00735 | 20030 | 01204 | |
| 00646 | RSH | A*1 | 00736 | 15030 | 01204 | |
| 00647 | ADD | A*W(WIDTH) | 00737 | 11030 | 01205 | INCREASE WIDTH BY .5 |
| 00650 | STR | A*W(WIDTH) | 00740 | 02000 | 00001 | |
| 00651 | JP | SEARCH101 | 00741 | 20030 | 01205 | |
| 00652 | WIDTHIN | 0000314631 | 00742 | 15030 | 01205 | |
| 00653 | LENGTHIN | 0004000000 | 00743 | 61000 | 00726 | .4818 KEYBOARD ENTERED WIDTH |
| 00654 | JP | SC1 | 00744 | 00003 | 14631 | .4818 KEYBOARD ENTERED LENGTH |
| 00655 | CL | W(CROSSCAN) | 00745 | 00040 | 00000 | SET CROSSCAN TO ZERO |
| 00656 | CL | W(ACROSSCAN) | 00746 | 61000 | 01027 | |
| 00657 | CL | W(ECROSSCAN) | 00747 | 16030 | 00552 | |
| 00660 | ENT | A*-1 | 00750 | 16030 | 00554 | I= -N-1 |
| 00661 | SUB | A*W(N) | 00751 | 16030 | 00553 | |
| 00662 | STR | A*W(I) | 00752 | 11040 | 77776 | |
| 00663 | ENT | Q*W(SCMINEL) | 00753 | 21030 | 00562 | |
| 00664 | SUB | Q*W(ELEVSH*3) | 00754 | 15030 | 00561 | |
| 00665 | STR | Q*W(ELPOINT) | 00755 | 10030 | 01206 | |
| | | | 00756 | 27030 | 00501 | EL = MINIMUM SCAN ELEVATION |
| | | | 00757 | 14030 | 00574 | |

| | | | | | |
|-------|------------|-------------------------|-------|-------|-------|
| 00666 | JP | AZT0G0WEL | 00760 | 61000 | 01051 |
| 00667 | SEARCHSCAN | | 00761 | 12000 | 00000 |
| 00670 | | ENT G*W(ELEVSH+5) | 00762 | 10030 | 00503 |
| 00671 | | SUB G*W(ELEVSH+3) | 00763 | 27030 | 00501 |
| 00672 | | STR G*W(ELDIF20) | 00764 | 14030 | 00570 |
| 00673 | | MUL W(ELDIF20) | 00765 | 22030 | 00570 |
| 00674 | | LSH AG*6 | 00766 | 07000 | 00006 |
| 00675 | | STR A*W(ELDIF20SQ) | 00767 | 15030 | 00571 |
| 00676 | | ENT G*W(ELEVSH+2) | 00770 | 10030 | 00500 |
| 00677 | | SUB G*W(ELEVSH+3) | 00771 | 27030 | 00501 |
| 00700 | | STR G*W(ELDIFM10) | 00772 | 14030 | 00567 |
| 00701 | | ENT G*W(AZIMSH+2) | 00773 | 10030 | 00472 |
| 00702 | | SUB G*W(AZIMSH+3) | 00774 | 27030 | 00473 |
| 00703 | | STR G*W(AZDIFM10) | 00775 | 14030 | 00565 |
| 00704 | | ENT G*W(AZIMSH+5) | 00776 | 10030 | 00475 |
| 00705 | | SUB G*W(AZIMSH+3) | 00777 | 27030 | 00473 |
| 00706 | | STR G*W(AZDIF20) | 01000 | 14030 | 00566 |
| 00707 | | MUL W(AZDIF20) | 01001 | 22030 | 00566 |
| 00710 | | LSH AG*6 | 01002 | 07000 | 00006 |
| 00711 | | STR A*W(AZDIF20SQ) | 01003 | 15030 | 00572 |
| 00712 | | ENT A*W(ELEVSH+5) | 01004 | 11030 | 00503 |
| 00713 | | SUB A*W(HORIZTEST)*AP05 | 01005 | 21630 | 00564 |
| 00714 | | JP BELOWHORIZ | 01006 | 61000 | 00747 |
| 00715 | | ENT A*W(AZDIF20SQ) | 01007 | 11030 | 00572 |
| 00716 | | ADD A*W(ELDIF20SQ) | 01010 | 20030 | 00571 |
| 00717 | | RJP SQR | 01011 | 65000 | 00504 |
| 00720 | | JP ENDANGLE+1 | 01012 | 61000 | 01023 |
| 00721 | | STR A*W(SQRTDEN)*AN0T | 01013 | 15330 | 00573 |
| 00722 | | JP ENDANGLE+1 | 01014 | 61000 | 01023 |
| 00723 | | ENT A*W(ELDIF20) | 01015 | 11030 | 00570 |
| 00724 | | DIV W(SQRTDEN) | 01016 | 23030 | 00573 |
| 00725 | | STR G*W(SCSIN) | 01017 | 14030 | 00556 |
| 00726 | | ENT A*W(AZDIF20) | 01020 | 11030 | 00566 |
| 00727 | | DIV W(SQRTDEN) | 01021 | 23030 | 00573 |
| 00730 | ENDANGLE | STR G*W(SCCOS) | 01022 | 14030 | 00557 |
| 00731 | | ENT A*W(I)*ANEG | 01023 | 11730 | 00561 |
| 00732 | | JP SC4 | 01024 | 61000 | 00672 |
| 00733 | | ADD A*W(N)*AP05 | 01025 | 20630 | 00562 |
| 00734 | | JP SC3 | 01026 | 61000 | 00660 |
| 00735 | SC1 | ENT G*W(I)*QP05 | 01027 | 10230 | 00561 |
| 00736 | | STR G*Q | 01030 | 14000 | 00000 |
| 00737 | | SUB G*W(SCANLIN) | 01031 | 27030 | 00550 |
| 00740 | | MUL W(I) | 01032 | 22030 | 00561 |
| 00741 | | MUL W(SCANACCNEG) | 01033 | 22030 | 00551 |
| 00742 | | RSH AG*2 | 01034 | 03000 | 00002 |
| 00743 | | STR G*W(SCANP0INT) | 01035 | 14030 | 00563 |
| 00744 | SC10 | RPL Y+1*W(I) | 01036 | 36030 | 00561 |
| 00745 | SC2 | ENT A*W(AZDIF20)*AP05 | 01037 | 11630 | 00566 |
| 00746 | | STR A*A | 01040 | 15040 | 00000 |
| 00747 | | ENT G*W(ELDIF20)*QP05 | 01041 | 10230 | 00570 |
| 00750 | | STR G*Q | 01042 | 14000 | 00000 |
| 00751 | | SUB G*W*QP05 | 01043 | 27670 | 00000 |
| 00752 | | JP SC5 | 01044 | 61000 | 00605 |
| 00753 | | ENT G*W(SCANP0INT) | 01045 | 10030 | 00563 |
| 00754 | | MUL W(SCSIN) | 01046 | 22030 | 00556 |
| 00755 | | LSH AG*2 | 01047 | 07000 | 00002 |
| 00756 | | STR A*W(ELP0INT) | 01050 | 15030 | 00574 |
| 00757 | AZT0G0WEL | ENT G*W(ELDIF20) | 01051 | 10030 | 00570 |
| 00760 | | SUB G*W(ELDIFM10) | 01052 | 27030 | 00567 |

SET UP DIFFERENCES

B27 E2 - F0

B30 (E2 - E0)SQ

B27 E-1 - E0

B27 A-1 - A0

B27 A2 - A0

B30 (A2 - A0)SQ

IS ELEVATIO BELOW HORIZON

B29 SQUARE ROOT OF DENOM

B28 SINE OF ANGLE

B28 COSINE OF ANGLE
IS I POSITIVE

IS SCAN AT LOWER END

IS MAG(DIFEL-DIFAZ) P05

B27 ELEVATION SCAN

| | | | | | | |
|-------|-------|----------------|-------|-------|-------|--------------------------------|
| 00761 | MUL | W(ELDIF20) | 01053 | 22030 | 00570 | |
| 00762 | RSH | AQ*18D | 01054 | 03000 | 00022 | B36 |
| 00763 | MUL | W(ELDIFM10) | 01055 | 22030 | 00567 | |
| 00764 | LSH | AQ*12D*AN0T | 01056 | 07500 | 00014 | |
| 00765 | JP | ENDFIT+1 | 01057 | 61000 | 01117 | B45 DEN OF QUADRATIC |
| 00766 | STR | A*(FITDENOM) | 01060 | 15030 | 00602 | |
| 00767 | ENT | Q*(AZDIFM10) | 01061 | 10030 | 00565 | |
| 00770 | MUL | W(ELDIF20) | 01062 | 22030 | 00570 | |
| 00771 | LSH | AQ*12D | 01063 | 07000 | 00014 | |
| 00772 | STR | A*(JUNK) | 01064 | 15030 | 00577 | B36 |
| 00773 | ENT | Q*(AZDIF20) | 01065 | 10030 | 00566 | |
| 00774 | MUL | W(ELDIFM10) | 01066 | 22030 | 00567 | |
| 00775 | LSH | AQ*12D | 01067 | 07000 | 00014 | B36 |
| 00776 | STR | A*(JUNK+1) | 01070 | 15030 | 00600 | |
| 00777 | SUB | A*(JUNK) | 01071 | 21030 | 00577 | |
| 01000 | RSH | AQ*3 | 01072 | 03000 | 00003 | |
| 01001 | DIV | W(FITDENOM) | 01073 | 23030 | 00602 | B18 QUADRATIC COEFFICIENT |
| 01002 | STR | Q*(FITQUAD) | 01074 | 14030 | 00603 | |
| 01003 | ENT | Q*(JUNK+1) | 01075 | 10030 | 00600 | |
| 01004 | MUL | W(ELDIFM10) | 01076 | 22030 | 00567 | |
| 01005 | LSH | AQ*12D | 01077 | 07000 | 00014 | |
| 01006 | STR | A*(JUNK+1) | 01100 | 15030 | 00600 | B45 |
| 01007 | ENT | Q*(JUNK) | 01101 | 10030 | 00577 | |
| 01010 | MUL | W(ELDIF20) | 01102 | 22030 | 00570 | |
| 01011 | LSH | AQ*12D | 01103 | 07000 | 00014 | |
| 01012 | SUB | A*(JUNK+1) | 01104 | 21030 | 00600 | B45 |
| 01013 | RSH | AQ*15D | 01105 | 03000 | 00017 | |
| 01014 | DIV | W(FITDENOM) | 01106 | 23030 | 00602 | B15 LINEAR COEFFICIENT |
| 01015 | STR | Q*(FITLIN) | 01107 | 14030 | 00604 | |
| 01016 | ENT | Q*(FITQUAD) | 01110 | 10030 | 00603 | |
| 01017 | MUL | W(ELPOINT) | 01111 | 22030 | 00574 | B15 |
| 01020 | ADD | A*(FITLIN) | 01112 | 20030 | 00604 | |
| 01021 | ENT | Q*A | 01113 | 10070 | 00000 | |
| 01022 | MUL | W(ELPOINT) | 01114 | 22030 | 00574 | B12 |
| 01023 | LSH | AQ*15D | 01115 | 07000 | 00017 | |
| 01024 | STR | A*(AZPOINT) | 01116 | 15030 | 00575 | AZIMUTH TO 60 WITH ELEVATION B |
| 01025 | ENT | A*1 | 01117 | 11000 | 00001 | 27 |
| 01026 | ENT | Q*(SCANMODE) | 01120 | 10030 | 00576 | SET SCANMODE TO SEARCHSCAN |
| 01027 | RSH | AQ*15D | 01121 | 03000 | 00017 | 1 INDICATE SEARCH SCAN |
| 01030 | STR | Q*(SCANMODE) | 01122 | 14030 | 00576 | |
| 01031 | ENT | A*(AZIMSH+5) | 01123 | 11030 | 00475 | |
| 01032 | ADD | A*(AZPOINT) | 01124 | 20030 | 00575 | |
| 01033 | ADD | A*(ACROSSCAN) | 01125 | 20030 | 00554 | |
| 01034 | STR | A*(ACGAZIM+3) | 01126 | 15030 | 63074 | |
| 01035 | ENT | A*(ELEVSH+5) | 01127 | 11030 | 00503 | |
| 01036 | ADD | A*(ELPOINT) | 01130 | 20030 | 00574 | |
| 01037 | ADD | A*(ECROSSCAN) | 01131 | 20030 | 00553 | |
| 01040 | STR | A*(ACGELEV+3) | 01132 | 15030 | 63100 | |
| 01041 | JP | L(ACQUIRUN) | 01133 | 61010 | 00360 | |
| 01042 | ENTRY | | 01134 | 61000 | 00000 | |
| 01043 | ENT | Q*(LENGTH) | 01135 | 10030 | 01204 | |
| 01044 | CL | A | 01136 | 11000 | 00000 | B3 |
| 01045 | DIV | W(MAXSCACC) | 01137 | 23030 | 01203 | |
| 01046 | LSH | AQ*31D | 01140 | 07000 | 00037 | |
| 01047 | RJP | SGRT | 01141 | 65000 | 00504 | B16 |
| 01050 | ENT | A*(NARBITRARY) | 01142 | 11030 | 01207 | SGRT ERROR MAKE N=NARBITRARY |
| 01051 | ADD | A*(NRROUND) | 01143 | 20030 | 01210 | |
| 01052 | RSH | AQ*17D | 01144 | 03000 | 00021 | |

| | | | | | |
|-------|------------|----------------|-------|-------|-------|
| 01053 | STR | A*(N) | 01145 | 15030 | 00562 |
| 01054 | LSH | A*1 | 01146 | 06000 | 00001 |
| 01055 | STR | A*(SCANLIN) | 01147 | 15030 | 00550 |
| 01056 | ENT | G*(N) | 01150 | 10030 | 00562 |
| 01057 | MUL | W(N) | 01151 | 22030 | 00562 |
| 01060 | STR | G*(JUNK) | 01152 | 14030 | 00577 |
| 01061 | ENT | G*(LENGTH) | 01153 | 10030 | 01204 |
| 01062 | LSH | AG*9D | 01154 | 07000 | 00011 |
| 01063 | DIV | W(JUNK) | 01155 | 23030 | 00577 |
| 01064 | MUL | W(RECIPREV) | 01156 | 22030 | 01202 |
| 01065 | RSH | AG*29D | 01157 | 03000 | 00035 |
| 01066 | STR | G* | 01160 | 14000 | 00000 |
| 01067 | STR | G*(SCANACCNeg) | 01161 | 14030 | 00551 |
| 01070 | ENT | A*-1 | 01162 | 11040 | 77776 |
| 01071 | SUB | A*(N) | 01163 | 21030 | 00562 |
| 01072 | STR | A*(I) | 01164 | 15030 | 00561 |
| 01073 | CL | W(CROSSCAN) | 01165 | 16030 | 00552 |
| 01074 | CL | W(ECROSSCAN) | 01166 | 16030 | 00553 |
| 01075 | CL | W(ACROSSCAN) | 01167 | 16030 | 00554 |
| 01076 | ENT | G*(WIDTH) | 01170 | 10030 | 01205 |
| 01077 | MUL | W(RECIPREV) | 01171 | 22030 | 01202 |
| 01100 | LSH | AG*8D | 01172 | 07000 | 00010 |
| 01101 | STR | A*(CRSCW) | 01173 | 15030 | 00560 |
| 01102 | ENT | G*(LENGTH) | 01174 | 10030 | 01204 |
| 01103 | MUL | W(RECIPREV) | 01175 | 22030 | 01202 |
| 01104 | RSH | AG*22D | 01176 | 03000 | 00026 |
| 01105 | ADD | G*(SCMINEL) | 01177 | 26030 | 01206 |
| 01106 | STR | G*(HORIZTEST) | 01200 | 14030 | 00564 |
| 01107 | EXIT | | 01201 | 61010 | 01134 |
| 01110 | RECIPREV | 0013301330 | 01202 | 00133 | 01330 |
| 01111 | MAXSCACC | 0000000507 | 01203 | 00000 | 00507 |
| 01112 | LENGTH | 0012000000 | 01204 | 00120 | 00000 |
| 01113 | WIDTH | 0001000000 | 01205 | 00010 | 00000 |
| 01114 | SCMINEL | 0001014223 | 01206 | 00010 | 14223 |
| 01115 | NARBITRARY | 100000 | 01207 | 00001 | 00000 |
| 01116 | NROUND | 340000 | 01210 | 00003 | 40000 |
| 01117 | RP2AVG2A | 0 | 01211 | 00000 | 00000 |
| 01120 | RP2AVG8A | 0 | 01212 | 00000 | 00000 |
| 01121 | RP2AVGSA | 0 | 01213 | 00000 | 00000 |
| 01122 | RP2AVGLA | 0 | 01214 | 00000 | 00000 |
| 01123 | RP2CODE2 | 0 | 01215 | 00000 | 00000 |
| 01124 | RP2CODE8 | 0 | 01216 | 00000 | 00000 |
| 01125 | RP2CODES | 0 | 01217 | 00000 | 00000 |
| 01126 | RP2CODEL | 0 | 01220 | 00000 | 00000 |
| 01127 | LOCCK | EQUALS | | | |
| 01130 | RAIUS | 0 | 01221 | 00000 | 00000 |
| 01131 | AVGBCW | 0 | 01222 | 00000 | 00000 |
| 01132 | DELRAIUS | 0000035062 | 01223 | 00000 | 35062 |
| 01133 | MAXRAIUS | 0000127434 | 01224 | 00001 | 27434 |

B0 2N

B27 IN 0

B27 ACC IN DEGREES/SEC

B30 NEGATIVE COMPUTED SCAN ACC
ELERATION

SET I= -N-1

B27 CROSSCAN WIDTH/2 IN REVOLU
TIONS

SET UP HORIZON TEST CONSTANT

B30 1/360

•01815 B15 MAXIMUM ALLOWABLE A
CCELERATION DEG
10818 B18 LENGTH OF SCAN DEGRE
ES

1818 B18 WIDTH OF SCAN DEGREES

•002827 MINIMUM ELEVATION FOR
SEARCH SCAN
ARBITRARY N B16

AVERAGE OVER 2 SEC INTERVAL
AVERAGE OVER 8 SEC INTERVAL
AVERAGE OVER LAST SEARCH SCAN
INTERVAL

AVERAGE OVER LAST LOCAL SCAN I
NTERVAL

RP2 CODES TO TELL IF SOMETHING
IS IN

THE ABOVE REGISTERS
0 MEANS NO CONTENTS (IN L)
NONZERO MEANS SOMETHING IN THE
AVG

K FOR SCAN IN U

•000111B27

•000334B27

| | | | | | | | |
|-------|-------------|-----------------------|----------|-------|-------|-------|--|
| 01134 | LOCSCABIAS | 0 | | 01225 | 00000 | 00000 | B27 COMPUTED LOCAL SCAN AZIMUT H BIAS |
| 01135 | WEIGHTSUM | 0 | | 01226 | 00000 | 00000 | SUM OF WEIGHTS FOR RP2 PULSES |
| 01136 | LOCSCBIAS | 0 | | 01227 | 00000 | 00000 | B27 COMPUTED LOCAL SCAN ELEVAT ION BIAS |
| 01137 | RP2AVG2E | 0 | | 01230 | 00000 | 00000 | |
| 01140 | RP2AVG8E | 0 | | 01231 | 00000 | 00000 | |
| 01141 | RP2AVGSE | 0 | | 01232 | 00000 | 00000 | |
| 01142 | RP2AVGLE | 0 | | 01233 | 00000 | 00000 | |
| 01143 | FIVEHUND | 4980 0 | | 01234 | 00762 | 00000 | |
| 01144 | GOODLSCNT | EQUALS | RP2CODES | | | | |
| 01145 | LOCSCCTABLE | -1 -1 | | 01235 | 77776 | 77776 | NO OF GOOD LOCAL SCANS IN U |
| 01146 | | -1 1 | | 01236 | 77776 | 00001 | 1ST SCAN, 1ST POINT (OLDEST) |
| 01147 | | 1 1 | | 01237 | 00001 | 00001 | 2ND AZ IN U, EL IN L |
| 01150 | | 1 -1 | | 01240 | 00001 | 77776 | 3RD |
| 01151 | | -1 -1 | | 01241 | 77776 | 77776 | 4TH |
| 01152 | | 0 1 | | 01242 | 00000 | 00001 | 5TH |
| 01153 | | 1 0 | | 01243 | 00001 | 00000 | 1ST SCAN, 2ND POINT |
| 01154 | | 0 -1 | | 01244 | 00000 | 77776 | |
| 01155 | | -1 0 | | 01245 | 77776 | 00000 | |
| 01156 | | 0 1 | | 01246 | 00000 | 00001 | |
| 01157 | | 1 0 | | 01247 | 00001 | 00000 | 1ST SCAN, 3RD POINT |
| 01160 | | 0 -1 | | 01250 | 00000 | 77776 | |
| 01161 | | -1 0 | | 01251 | 77776 | 00000 | |
| 01162 | | 0 1 | | 01252 | 00000 | 00001 | |
| 01163 | | 1 0 | | 01253 | 00001 | 00000 | |
| 01164 | | -1 -1 | | 01254 | 77776 | 77776 | 1ST SCAN, 4TH POINT |
| 01165 | | -1 1 | | 01255 | 77776 | 00001 | |
| 01166 | | 1 1 | | 01256 | 00001 | 00001 | |
| 01167 | | 1 -1 | | 01257 | 00001 | 77776 | |
| 01170 | GETAVG8 | -1 -1 | | 01260 | 77776 | 77776 | |
| 01171 | | ENTRY | | 01261 | 61000 | 00000 | |
| 01172 | | ENT A*(RP2AVG8A) | | 01262 | 11030 | 01212 | GET AZ AVERAGE |
| 01173 | | ADD A*(RP2AVG2A) | | 01263 | 20030 | 01211 | |
| 01174 | | STR A*(RP2AVG8A) | | 01264 | 15030 | 01212 | |
| 01175 | | ENT A*(RP2AVG8E) | | 01265 | 11030 | 01231 | GET EL AVERAGE |
| 01176 | | ADD A*(RP2AVG2E) | | 01266 | 20030 | 01230 | |
| 01177 | | STR A*(RP2AVG8E) | | 01267 | 15030 | 01231 | |
| 01200 | | RPL Y+1*(RP2C0DE8) | | 01270 | 36010 | 01216 | INCREASE CODE BY ONE |
| 01201 | | CL L(RP2C0DE2) | | 01271 | 16010 | 01215 | CLEAR 2SEC CODE |
| 01202 | | EXIT | | 01272 | 61010 | 01261 | |
| 01203 | AVGAZ0CY | ENT B6*(RP2TABLEID) | | 01273 | 12620 | 02576 | |
| 01204 | | ENT Q*(WEIGHTTTID) | | 01274 | 10020 | 02646 | |
| 01205 | | CL U(RP2C0UNT) | | 01275 | 16020 | 02573 | |
| 01206 | | JP AVGR0UTINE | | 01276 | 61000 | 01304 | |
| 01207 | INTERAZCY | ENT A*(RP2C0UNT)*ANOT | | 01277 | 11510 | 02573 | ANY RP2 PULSES |
| 01210 | | JP NORP2PULSE | | 01300 | 61000 | 00421 | |
| 01211 | | ENT B6*(RP2TABLEID) | | 01301 | 12610 | 02576 | |
| 01212 | | ENT Q*(WEIGHTTTID) | | 01302 | 10010 | 02646 | |
| 01213 | | CL L(RP2C0UNT) | | 01303 | 16010 | 02573 | |
| 01214 | AVGR0UTINE | STR Q*(AVGL00P+2) | | 01304 | 14010 | 01322 | |
| 01215 | | STR Q*(AVGL00P+6) | | 01305 | 14010 | 01326 | |
| 01216 | | CL W(AVGBCW) | | 01306 | 16030 | 01222 | |
| 01217 | | CL W(WEIGHTSUM) | | 01307 | 16030 | 01226 | |
| 01220 | | CL B7 | | 01310 | 12700 | 00000 | |
| 01221 | | RSH A*2 | | 01311 | 02000 | 00002 | |
| 01222 | | SUB A*1 | | 01312 | 21000 | 00001 | |
| 01223 | | STR A*(AVGL00P+11) | | 01313 | 15010 | 01331 | |

| | | | | | |
|-------|-----|--------------------|-------|-------|-------|
| 01224 | ENT | B6*3+B6 | 01314 | 12606 | 00003 |
| 01225 | STR | B6*L(AVGLOOP) | 01315 | 16610 | 01320 |
| 01226 | STR | B6*L(AVGLOOP+1) | 01316 | 16610 | 01321 |
| 01227 | CL | B6 | 01317 | 12600 | 00000 |
| 01230 | ENT | Q*U(B6) | 01320 | 10026 | 00000 |
| 01231 | SUB | Q*L(B6) | 01321 | 27016 | 00000 |
| 01232 | MUL | W(B7) | 01322 | 22037 | 00000 |
| 01233 | ADD | Q*W(AVGBCW) | 01323 | 26030 | 01222 |
| 01234 | STR | Q*W(AVGBCW) | 01324 | 14030 | 01222 |
| 01235 | ENT | A*W(WEIGHTSUM) | 01325 | 11030 | 01226 |
| 01236 | ADD | A*W(B7) | 01326 | 20037 | 00000 |
| 01237 | STR | A*W(WEIGHTSUM) | 01327 | 15036 | 01226 |
| 01240 | ENT | B6*4+B6 | 01330 | 12606 | 00004 |
| 01241 | BSK | B7*0 | 01331 | 71700 | 00000 |
| 01242 | JP | AVGL00P | 01332 | 61000 | 01320 |
| 01243 | CL | A | 01333 | 11000 | 00000 |
| 01244 | LSH | AQ*15D | 01334 | 07000 | 00017 |
| 01245 | DIV | W(WEIGHTSUM) | 01335 | 23030 | 01226 |
| 01246 | ADD | Q*40000 | 01336 | 26000 | 40000 |
| 01247 | SUB | Q*W(FIVEHUND)*QP0S | 01337 | 27630 | 01234 |
| 01250 | ADD | Q*W(FIVEHUND)*SKIP | 01340 | 26130 | 01234 |
| 01251 | ENT | Q*W(FIVEHUND) | 01341 | 10030 | 01234 |
| 01252 | STR | Q*W(AVGBCW) | 01342 | 14030 | 01222 |
| 01253 | ENT | A*U(AVGBCW) | 01343 | 11020 | 01222 |
| 01254 | CL | Q | 01344 | 10000 | 00000 |
| 01255 | DIV | 4000D | 01345 | 23000 | 07640 |
| 01256 | STR | Q*W(ACQY) | 01346 | 14030 | 02051 |
| 01257 | MUL | W(ACQY) | 01347 | 22030 | 02051 |
| 01260 | LSH | AQ*3 | 01350 | 07000 | 00003 |
| 01261 | STR | A*W(ACQYSQ) | 01351 | 15030 | 02052 |
| 01262 | ENT | Q*A | 01352 | 10070 | 00000 |
| 01263 | MUL | W(ACQY) | 01353 | 22030 | 02051 |
| 01264 | LSH | AQ*3 | 01354 | 07000 | 00003 |
| 01265 | STR | A*W(ACQYCUBE) | 01355 | 15030 | 02053 |
| 01266 | ENT | Q*W(ACQY) | 01356 | 10030 | 02051 |
| 01267 | MUL | W(THIRD) | 01357 | 22030 | 02054 |
| 01270 | STR | A*W(JUNK) | 01360 | 15030 | 00577 |
| 01271 | ENT | Q*W(ACQYCUBE) | 01361 | 10030 | 02053 |
| 01272 | MUL | W(THIRD) | 01362 | 22030 | 02054 |
| 01273 | STR | A*W(JUNK+1) | 01363 | 15030 | 00600 |
| 01274 | SUB | A*W(JUNK) | 01364 | 21030 | 00577 |
| 01275 | RSH | A*1 | 01365 | 02000 | 00001 |
| 01276 | STR | A*W(ACQA+3) | 01366 | 15030 | 02061 |
| 01277 | ENT | A*W(ACQYSQ) | 01367 | 11030 | 02052 |
| 01300 | SUB | A*W(ACQYCUBE) | 01370 | 21030 | 02053 |
| 01301 | RSH | A*1 | 01371 | 02000 | 00001 |
| 01302 | ADD | A*W(ACQY) | 01372 | 20030 | 02051 |
| 01303 | STR | A*W(ACQA+2) | 01373 | 15030 | 02060 |
| 01304 | ENT | A*W(ACQYCUBE) | 01374 | 11030 | 02053 |
| 01305 | SUB | A*W(ACQY) | 01375 | 21030 | 02051 |
| 01306 | RSH | A*1 | 01376 | 02000 | 00001 |
| 01307 | SUB | A*W(ACQYSQ) | 01377 | 21030 | 02052 |
| 01310 | ADD | A*W(ACQA1) | 01400 | 20030 | 02062 |
| 01311 | STR | A*W(ACQA+1) | 01401 | 15030 | 02057 |
| 01312 | ENT | A*W(ACQYSQ) | 01402 | 11030 | 02052 |
| 01313 | SUB | A*W(JUNK+1) | 01403 | 21030 | 00600 |
| 01314 | RSH | A*1 | 01404 | 02000 | 00001 |

COMPUTE AVERAGE BCW

AVG BCW IN AVGBCW AND Q WITH B
15

ROUNDED BCW IN U(AVGBCW)
COMPUTE INTERPOLATION COEFFICI
ENTS

FOR THE AVG BCW

B27 Y

B27 YY

B27 YYY

B27 (113)Y

B27 (1/3)YYY

A2

A1

A0

| | | | | | | | |
|---|-------|------------|-------------------------|---------------|-------|-------|---------------------------------------|
| • | 01315 | SUB | A*(JUNK) | 1405 | 21030 | 00577 | |
| • | 01316 | STR | A*(ACGA) | 1406 | 15030 | 02056 | |
| • | 01317 | PUT | 1*L(RP2C0DE2) | 1407 | 10000 | 00001 | A-1 SET RP2AVG2 CODE |
| • | 01320 | CL | W(RP2AVG2E) | 1410 | 14010 | 01215 | COMPUTE ELEVATION PREDICTED VA LUE |
| • | 01321 | ENT | B6*3 | 1412 | 12600 | 00003 | |
| • | 01322 | ENT | Q*(ACGA+B6) | 1413 | 10036 | 02056 | |
| • | 01323 | MUL | W(ELEVSH+B6) | 1414 | 22036 | 00476 | |
| • | 01324 | LSH | AQ*3 | 1415 | 07000 | 00003 | |
| • | 01325 | ADD | A*(RP2AVG2E) | 1416 | 20030 | 01230 | |
| • | 01326 | STR | A*(RP2AVG2E) | 1417 | 15030 | 01230 | |
| • | 01327 | BJP | B6*\$-5 | 1420 | 72600 | 01413 | |
| • | 01330 | CL | W(RP2AVG2A) | 1421 | 16030 | 01211 | COMPUTE AZIMUTH PREDICTED VALU E |
| • | 01331 | ENT | B6*3 | 1422 | 12600 | 00003 | |
| • | 01332 | ENT | Q*(ACGA+B6) | 1423 | 10036 | 02056 | |
| • | 01333 | MUL | W(AZIMSH+B6) | 1424 | 22036 | 00470 | |
| • | 01334 | LSH | AQ*3 | 1425 | 07000 | 00003 | |
| • | 01335 | ADD | A*(RP2AVG2A) | 1426 | 20030 | 01211 | |
| • | 01336 | STR | A*(RP2AVG2A) | 1427 | 15030 | 01211 | |
| • | 01337 | BJP | B6*\$-5 | 1430 | 72600 | 01423 | |
| • | 01340 | ENT | A*(AVGBCW) | 1431 | 11020 | 01222 | |
| • | 01341 | ADD | A*(INAZIMADD) | 1432 | 20010 | 63446 | |
| • | 01342 | STR | A*(S+1) | 1433 | 15010 | 01434 | |
| • | 01343 | ENT | A*(0) | 1434 | 11030 | 00000 | |
| • | 01344 | SEL | CL*7774000000 | 1435 | 52030 | 02774 | |
| • | 01345 | CL | Q | 1436 | 10000 | 00000 | |
| • | 01346 | LSH | AQ*10D*AP0S | 1437 | 07600 | 00012 | |
| • | 01347 | JP | INOVERLAP | 1440 | 61000 | 01475 | |
| • | 01350 | NONOVERLAP | AQ*2 | 1441 | 03000 | 00002 | |
| • | 01351 | SUB | A*(RP2AVG2A) | 1442 | 21030 | 01211 | |
| • | 01352 | STR | A*(RP2AVG2A) | 1443 | 15030 | 01211 | |
| • | 01353 | ENT | A*(AVGBCW) | 1444 | 11020 | 01222 | COMPUTE ELEVATION AVERAGE ERRO R |
| • | 01354 | WFHSACQUI2 | ADD | A*(INELEVADD) | 1445 | 20010 | 63447 |
| • | 01355 | STR | A*(S+1) | 1446 | 15010 | 01447 | |
| • | 01356 | ENT | A*(0) | 1447 | 11030 | 00000 | |
| • | 01357 | SEL | CL*7776000000 | 1450 | 52030 | 02775 | |
| • | 01360 | CL | Q | 1451 | 10000 | 00000 | |
| • | 01361 | LSH | AQ*11D*AP0S | 1452 | 07600 | 00013 | |
| • | 01362 | SUB | A*2000 | 1453 | 21000 | 02000 | |
| • | 01363 | RSH | AQ*3 | 1454 | 03000 | 00003 | |
| • | 01364 | SUB | A*(RP2AVG2E) | 1455 | 21030 | 01230 | |
| • | 01365 | STR | A*(RP2AVG2E) | 1456 | 15030 | 01230 | |
| • | 01366 | ENT | A*(SCANMODE)*AZERO | 1457 | 11420 | 00576 | PRESENT SCANMODE LOCAL |
| • | 01367 | JP | FIRSTLOC | 1460 | 61000 | 01612 | |
| • | 01370 | ENT | A*(SCANMODE)*AN0T | 1461 | 11510 | 00576 | PREVIOUS SCANMODE LOCAL |
| • | 01371 | JP | LOCALSCAN | 1462 | 61000 | 01473 | |
| • | 01372 | PUT | W(RP2AVG2A)*W(RP2AVGSA) | 1463 | 10030 | 01211 | STORE LEFT OVER SEARCH RP2 |
| • | 01373 | PUT | W(RP2AVG2E)*W(RP2AVGSE) | 1464 | 14030 | 01213 | |
| • | 01374 | CL | L(RP2C0DE2) | 1465 | 10030 | 01230 | |
| • | 01375 | PUT | 1*L(RP2C0DES) | 1466 | 14030 | 01232 | |
| • | 01376 | CL | L(RP2C0DE2) | 1467 | 16010 | 01215 | |
| • | 01377 | LOCALSCAN | ENT | 1470 | 10000 | 00001 | |
| • | 01400 | JP | B6*U(LOCCK) | 1471 | 14010 | 01217 | |
| • | | | L(KTABLE+B6) | 1472 | 16010 | 01215 | |
| • | | | | 1473 | 12620 | 01215 | |
| • | | | | 01474 | 61016 | 01502 | |

| | | | | | | | |
|---|-------|-----------|-----|-------------------------|-------|-------|-------|
| • | 01401 | INOVERLAP | LSH | AQ*1*AP05 | 01475 | 07600 | 00001 |
| • | 01402 | | RSH | AQ*3*SKIP | 01476 | 03100 | 00003 |
| • | 01403 | | LSH | AQ*S7D*SKIP | 01477 | 07100 | 00071 |
| • | 01404 | | SUB | A*200 | 01500 | 21000 | 00200 |
| • | 01405 | | JP | NONOVERLAP+1 | 01501 | 61000 | 01442 |
| • | 01406 | KTABLE | 0 | KIS0 | 01502 | 00000 | 01507 |
| • | 01407 | | 0 | KIS1 | 01503 | 00000 | 01511 |
| • | 01410 | | 0 | KIS2 | 01504 | 00000 | 01526 |
| • | 01411 | | 0 | KIS3 | 01505 | 00000 | 01530 |
| • | 01412 | | 0 | KIS4 | 01506 | 00000 | 01535 |
| • | 01413 | KIS0 | ENT | B6*1 | 01507 | 12600 | 00001 |
| • | 01414 | | JP | LOCSCC0MP1 | 01510 | 61000 | 01720 |
| • | 01415 | KIS1 | ENT | B6*2 | 01511 | 12600 | 00002 |
| • | 01416 | | ENT | A*W(RAIUS)*AZERO | 01512 | 11430 | 01221 |
| • | 01417 | | JP | LOCSCC0MP1 | 01513 | 61000 | 01720 |
| • | 01420 | | ENT | A*L(RP2C0DE2)*AN0T | 01514 | 11510 | 01215 |
| • | 01421 | | JP | LOCSCC0MP1 | 01515 | 61000 | 01720 |
| • | 01422 | | PUT | W(RP2AVG2E)*W(RP2AVGLE) | 01516 | 10030 | 01230 |
| • | 01423 | | PUT | W(RP2AVG2A)*W(RP2AVGLA) | 01517 | 14030 | 01233 |
| • | 01424 | | PUT | 1*L(RP2C0DE1) | 01520 | 10030 | 01211 |
| • | 01425 | | CL | L(RP2C0DE2) | 01521 | 14030 | 01214 |
| • | 01426 | | JP | LOCSCC0MP1 | 01522 | 10000 | 00001 |
| • | 01427 | KIS2 | ENT | B6*3 | 01523 | 14010 | 01220 |
| • | 01430 | | JP | LOCSCC0MP1 | 01524 | 16010 | 01215 |
| • | 01431 | KIS3 | ENT | B6*4 | 01525 | 61000 | 01720 |
| • | 01432 | | ENT | A*W(RAIUS) | 01526 | 12600 | 00003 |
| • | 01433 | | ADD | A*W(DELRADIUS) | 01527 | 61000 | 01720 |
| • | 01434 | | STR | A*W(RAIUS) | 01530 | 12600 | 00004 |
| • | 01435 | | JP | LOCSCC0MP1 | 01531 | 11030 | 01221 |
| • | 01436 | KIS4 | ENT | A*L(RP2C0DE2)*AZERO | 01532 | 20030 | 01223 |
| • | 01437 | | RJP | GETAVG8 | 01533 | 15030 | 01221 |
| • | 01440 | | ENT | A*L(RP2C0DE8)*AN0T | 01534 | 61000 | 01720 |
| • | 01441 | | JP | LASTTEST | 01535 | 11410 | 01215 |
| • | 01442 | | RPL | Y+1*U(G00DLSCNT) | 01536 | 65000 | 01261 |
| • | 01443 | | SUB | A*3*AP05 | 01537 | 11510 | 01216 |
| • | 01444 | | JP | NEWMEAN | 01540 | 61000 | 01572 |
| • | 01445 | | JP | ACQUIMSG*AZERO | 01541 | 36020 | 01217 |
| • | 01446 | | RPL | Y-1*U(G00DLSCNT) | 01542 | 21600 | 00003 |
| • | 01447 | | ENT | A*UX(TIMECODE)*ANEG | 01543 | 61000 | 01553 |
| • | 01450 | | JP | NEWMEAN | 01544 | 60400 | 02041 |
| • | 01451 | | PUT | -0*U(TIMECORRC) | 01545 | 37020 | 01217 |
| • | 01452 | NEWMEAN | CL | U(TIMECODE) | 01546 | 11760 | 00217 |
| • | 01453 | | ENT | A*W(RP2AVG8A) | 01547 | 61000 | 01553 |
| • | 01454 | | RSH | AQ*300 | 01550 | 10040 | 77777 |
| • | 01455 | | DIV | L(RP2C0DE8) | 01551 | 14020 | 02055 |
| • | 01456 | | STR | Q*W(LOCSCABIAS) | 01552 | 16020 | 00217 |
| • | 01457 | | ENT | A*W(RP2AVG8E) | 01553 | 11030 | 01212 |
| • | 01460 | | RSH | AQ*300 | 01554 | 03000 | 00036 |
| • | 01461 | | DIV | L(RP2C0DE8) | 01555 | 23010 | 01216 |
| • | 01462 | INITLOCSC | STR | Q*W(LOCSCBIBIAS) | 01556 | 14030 | 01225 |
| • | 01463 | | CL | W(RP2AVG8A) | 01557 | 11030 | 01231 |
| • | 01464 | | CL | W(RP2AVG8E) | 01561 | 23010 | 01216 |
| • | 01465 | | CL | U(LOCSCCK) | 01562 | 14030 | 01227 |
| • | 01466 | | CL | L(RP2C0DE8) | 01563 | 16030 | 01212 |
| | | | | | 01564 | 16030 | 01231 |
| | | | | | 01565 | 16020 | 01215 |
| | | | | | 01566 | 16010 | 01216 |

K IS 0
 K IS 1
 NO RP2 PULSES
 STORE LEFT OVER RP2 PULSE
 K IS 2
 K IS 3
 USE NEXT SCAN RADIUS
 ANY RP2 PULSES IN LAST 8 SEC
 COMPUTE LOCAL SCAN BIASES
 FROM THE AVERAGES ACCUMULATED
 OVER 8 SECOND INTERVAL
 SET K TO ZERO

| | | | | | | | |
|---|-------|-----|-------------------------|-------------|-------------|-------------|--------------------------------|
| • | 01467 | CL | W(RAIUS) | 16030 01221 | 01567 | 16030 01221 | |
| • | 01470 | CL | L(RP2CODE2) | 16010 01215 | 01570 | 16010 01215 | |
| • | 01471 | JP | LOCALSCAN | 01571 | 61000 01473 | | |
| • | 01472 | ENT | B0*1 | 01572 | 12600 00001 | | |
| • | 01473 | ENT | A*(RAIUS) | 01573 | 11030 01221 | | ALL THROUGH WITH LOCAL SCAN |
| • | 01474 | SUB | A*(MAXRAIUS)*AP05 | 01574 | 21630 01224 | | NO |
| • | 01475 | JP | LOCSCC0MP1 | 01575 | 61000 01720 | | |
| • | 01476 | ENT | A*(RP2CODE2)*AN0T | 01576 | 11530 01215 | | |
| • | 01477 | JP | FIRSTLOC | 01577 | 61000 01612 | | |
| • | 01500 | ENT | A*(RP2CODEL)*AN0T | 01600 | 11510 01220 | | ANY LEFT OVER LOCAL RP2 PULSES |
| • | 01501 | JP | LEFTSSCRP2 | 01601 | 61000 01622 | | NO |
| • | 01502 | CL | L(RP2CODEL) | 01602 | 16010 01220 | | INTERROGATE THE LOCAL RP2 |
| • | 01503 | PUT | W(RP2AVGLA)*W(RP2AVG8A) | 01603 | 10030 01214 | | |
| • | 01504 | PUT | W(RP2AVGLE)*W(RP2AVG8E) | 01604 | 14030 01212 | | |
| • | 01505 | ENT | Q*1 | 01605 | 10030 01233 | | |
| • | 01506 | STR | Q*(RP2CODE8) | 01606 | 14030 01231 | | |
| • | 01507 | JP | CLEARCOUNT | 01607 | 10000 00001 | | |
| • | 01510 | PUT | W(RP2AVG2A)*W(RP2AVG8A) | 01610 | 14010 01216 | | |
| • | 01511 | PUT | W(RP2AVG2E)*W(RP2AVG8E) | 01611 | 61000 01620 | | |
| • | 01512 | PUT | 1*(RP2CODE8) | 01612 | 10030 01211 | | |
| • | 01513 | CL | U(G00DLSCNT) | 01613 | 14030 01212 | | |
| • | 01514 | JP | NEWMEAN | 01614 | 10030 01230 | | |
| • | 01515 | CL | W(RAIUS) | 01615 | 14030 01231 | | |
| • | 01516 | ENT | A*(RP2CODES)*AN0T | 01616 | 10000 00001 | | |
| • | 01517 | JP | BACKUPSCAN | 01617 | 14010 01216 | | |
| • | 01520 | CL | L(RP2CODES) | 01620 | 16020 01217 | | |
| • | 01521 | PUT | W(RP2AVGSA)*W(RP2AVG8A) | 01621 | 61000 01553 | | |
| • | 01522 | PUT | W(RP2AVGSE)*W(RP2AVG8E) | 01622 | 16030 01221 | | INTERROGATE THE SEARCH RP2 |
| • | 01523 | JP | CLEARCOUNT-2 | 01623 | 11510 01217 | | |
| • | 01524 | ENT | A*(I)*AP05 | 01624 | 61000 01633 | | |
| • | 01525 | JP | NEG1 | 01625 | 16010 01217 | | |
| • | 01526 | ENT | Q*(SC10) | 01626 | 10030 01213 | | |
| • | 01527 | SUB | Q*36030*0ZER0 | 01627 | 14030 01212 | | |
| • | 01530 | JP | POSP05 | 01630 | 10030 01232 | | |
| • | 01531 | SUB | A*4 | 01631 | 14030 01231 | | |
| • | 01532 | STR | A*(I) | 01632 | 61000 01616 | | IS I POSITIVE |
| • | 01533 | JP | SEARCHSCAN+1 | 01633 | 11630 00561 | | NO |
| • | 01534 | ENT | Q*(SC10) | 01634 | 61000 01643 | | YES |
| • | 01535 | SUB | Q*37030*0ZER0 | 01635 | 10020 01036 | | GOING TOWARD END |
| • | 01536 | JP | \$+4 | 01636 | 27400 36030 | | NO |
| • | 01537 | ADD | A*4 | 01637 | 61000 01672 | | YES |
| • | 01540 | STR | A*(I) | 01641 | 15030 00561 | | I IS I-4 |
| • | 01541 | JP | SEARCHSCAN+1 | 01642 | 61000 00762 | | |
| • | 01542 | SUB | A*4 | 01643 | 10020 01036 | | GOING TOWARD END |
| • | 01543 | STR | A*(I) | 01644 | 27400 37030 | | NO |
| • | 01544 | ADD | A*(N)*ANEG | 01645 | 61000 01651 | | YES |
| • | 01545 | JP | SEARCHSCAN+1 | 01646 | 20000 00004 | | I IS I+4 |
| • | 01546 | STR | A*4 | 01647 | 15030 00561 | | |
| • | 01547 | SUB | A*(N) | 01650 | 61000 00762 | | |
| • | 01550 | SUB | A*1 | 01651 | 21000 00004 | | |
| • | 01551 | STR | A*(I) | 01652 | 15030 00561 | | IS IT LES THAN 4 FROM END |
| | | | | 01653 | 20730 00562 | | NO |
| | | | | 01654 | 61000 00762 | | I IS AT NEGATIVE END |
| | | | | 01655 | 15040 00000 | | |
| | | | | 01656 | 21030 00562 | | |
| | | | | 01657 | 21000 00001 | | |
| | | | | 01660 | 15030 00561 | | |

| | | | | | | |
|-------|------------|-------------------------|-------|-------|-------|-----------------------------|
| 01552 | ENT | A*(ECROSSCAN) | 01661 | 11030 | 00553 | COMPLIMENT CROSSCAN |
| 01553 | STR | A*A | 01662 | 15040 | 00000 | |
| 01554 | STR | A*(ECROSSCAN) | 01663 | 15030 | 00553 | |
| 01555 | ENT | A*(ACROSSCAN) | 01664 | 11030 | 00554 | |
| 01556 | STR | A*A | 01665 | 15040 | 00000 | |
| 01557 | STR | A*(ACROSSCAN) | 01666 | 15030 | 00554 | |
| 01560 | ENT | A*37030 | 01667 | 11000 | 37030 | MAKE SCAN GO THE OTHER WAY |
| 01561 | STR | A*(SC10) | 01670 | 15020 | 01036 | |
| 01562 | JP | SEARCHSCAN+1 | 01671 | 61000 | 00762 | |
| 01563 | ADD | A*4 | 01672 | 20000 | 00004 | I IS AT POSITIVE END |
| 01564 | STR | A*(I) | 01673 | 15030 | 00561 | |
| 01565 | SUB | A*(N)*AP05 | 01674 | 21630 | 00562 | |
| 01566 | JP | SEARCHSCAN+1 | 01675 | 61000 | 00762 | |
| 01567 | STR | A*A | 01676 | 15040 | 00000 | I IS AT POSITIVE END |
| 01570 | ADD | A*(N) | 01677 | 20030 | 00562 | |
| 01571 | SUB | A*1 | 01700 | 21000 | 00001 | |
| 01572 | STR | A*(I) | 01701 | 15030 | 00561 | |
| 01573 | ENT | Q*(CROSSCAN) | 01702 | 10030 | 00552 | SUBTRACT CROSSCAN INCREMENT |
| 01574 | SUB | Q*(DELGRSC) | 01703 | 27030 | 00555 | |
| 01575 | STR | Q*(CROSSCAN) | 01704 | 14030 | 00552 | |
| 01576 | MUL | W*(SCSIN) | 01705 | 22030 | 00556 | |
| 01577 | LSH | AG*2 | 01706 | 07000 | 00002 | |
| 01600 | STR | Q*Q | 01707 | 14000 | 00000 | |
| 01601 | STR | A*(ACROSSCAN) | 01710 | 15030 | 00554 | |
| 01602 | ENT | Q*(CROSSCAN) | 01711 | 10030 | 00552 | |
| 01603 | MUL | W*(SCCOS) | 01712 | 22030 | 00557 | |
| 01604 | LSH | AG*2 | 01713 | 07000 | 00002 | |
| 01605 | STR | A*(ECROSSCAN) | 01714 | 15030 | 00553 | |
| 01606 | ENT | A*36030 | 01715 | 11000 | 36030 | MAKE SCAN GO THE OTHER WAY |
| 01607 | STR | A*(SC10) | 01716 | 15020 | 01036 | |
| 01610 | JP | SEARCHSCAN+1 | 01717 | 61000 | 00762 | |
| 01611 | LOCSCCOMP1 | B6*(LOCSC) | 01720 | 16620 | 01215 | |
| 01612 | ENT | A*(RP2CODE2)*AZERO | 01721 | 11410 | 01215 | ANY RP2 PULSES |
| 01613 | RJP | GETAVG8 | 01722 | 65000 | 01261 | ADD THEM INTO THE SUM |
| 01614 | ENT | Q*(RAIUS) | 01723 | 10030 | 01221 | |
| 01615 | MUL | UX*(LOCSC*TABLE+B6) | 01724 | 22066 | 01235 | |
| 01616 | ADD | Q*(LOCSCABIAS) | 01725 | 26030 | 01225 | |
| 01617 | ADD | Q*(AZIMSH+2) | 01726 | 26030 | 00472 | |
| 01620 | STR | Q*(ACQAZIM) | 01727 | 14030 | 63071 | OLDEST AZ POINT AZ-1 |
| 01621 | ENT | Q*(RAIUS) | 01730 | 10030 | 01221 | |
| 01622 | MUL | UX*(LOCSC*TABLE+5*B6) | 01731 | 22066 | 01242 | |
| 01623 | ADD | Q*(LOCSCABIAS) | 01732 | 26030 | 01225 | |
| 01624 | ADD | Q*(AZIMSH+3) | 01733 | 26030 | 00473 | |
| 01625 | STR | Q*(ACQAZIM+1) | 01734 | 14030 | 63072 | AZ0 |
| 01626 | ENT | Q*(RAIUS) | 01735 | 10030 | 01221 | |
| 01627 | MUL | UX*(LOCSC*TABLE+10D+B6) | 01736 | 22066 | 01247 | |
| 01630 | ADD | Q*(LOCSCABIAS) | 01737 | 26030 | 01225 | |
| 01631 | ADD | Q*(AZIMSH+4) | 01740 | 26030 | 00474 | |
| 01632 | STR | Q*(ACQAZIM+2) | 01741 | 14030 | 63073 | AZ1 |
| 01633 | ENT | Q*(RAIUS) | 01742 | 10030 | 01221 | |
| 01634 | MUL | UX*(LOCSC*TABLE+15D+B6) | 01743 | 22066 | 01254 | |
| 01635 | ADD | Q*(LOCSCABIAS) | 01744 | 26030 | 01225 | |
| 01636 | ADD | Q*(AZIMSH+5) | 01745 | 26030 | 00475 | |
| 01637 | STR | Q*(ACQAZIM+3) | 01746 | 14030 | 63074 | AZ2 |
| 01640 | ENT | Q*(RAIUS) | 01747 | 10030 | 01221 | |
| 01641 | MUL | LX*(LOCSC*TABLE+B6) | 01750 | 22056 | 01235 | |
| 01642 | ADD | Q*(LOCSCABIAS) | 01751 | 26030 | 01227 | |
| 01643 | ADD | Q*(ELEVSH+2) | 01752 | 26030 | 00500 | |
| 01644 | STR | Q*(ACQELEV) | 01753 | 14030 | 63075 | EL-1 |

| | | | | | | | |
|---|-------|-----------|------------------------|-------|-------|-------|--------------------------------|
| • | 01645 | ENT | Q*W(RAIUS) | 01754 | 10030 | 01221 | |
| • | 01646 | MUL | LX(LOCSCCTABLE*5+B6) | 01755 | 22056 | 01242 | |
| • | 01647 | ADD | Q*W(LOCSCBIAS) | 01756 | 26030 | 01227 | |
| • | 01650 | ADD | Q*W(ELEVSH+3) | 01757 | 26030 | 00501 | EL0 |
| • | 01651 | STR | Q*W(ACQLEEV+1) | 01760 | 14030 | 63076 | |
| • | 01652 | ENT | Q*W(RAIUS) | 01761 | 10030 | 01221 | |
| • | 01653 | MUL | LX(LOCSCCTABLE*100*B6) | 01762 | 22056 | 01247 | |
| • | 01654 | ADD | Q*W(LOCSCBIAS) | 01763 | 26030 | 01227 | |
| • | 01655 | ADD | Q*W(ELEVSH+4) | 01764 | 26030 | 00502 | |
| • | 01656 | STR | Q*W(ACQLEEV+2) | 01765 | 14030 | 63077 | EL1 |
| • | 01657 | ENT | Q*W(RAIUS) | 01766 | 10030 | 01221 | |
| • | 01660 | MUL | LX(LOCSCCTABLE*150*B6) | 01767 | 22056 | 01254 | |
| • | 01661 | ADD | Q*W(LOCSCBIAS) | 01770 | 26030 | 01227 | |
| • | 01662 | ADD | Q*W(ELEVSH+5) | 01771 | 26030 | 00503 | |
| • | 01663 | STR | Q*W(ACQLEEV+3) | 01772 | 14030 | 63100 | |
| • | 01664 | ENT | Q*W(SCANMODE) | 01773 | 10030 | 00576 | SET MODE TO LOCAL |
| • | 01665 | CL | A | 01774 | 11000 | 00000 | |
| • | 01666 | RSH | AQ*150 | 01775 | 03000 | 00017 | |
| • | 01667 | STR | Q*W(SCANMODE) | 01776 | 14030 | 00576 | |
| • | 01670 | ENT | A*W(TIMECORRC)*ANEG | 01777 | 11730 | 02055 | |
| • | 01671 | JP | L(ACQUIRUN) | 02000 | 61010 | 00360 | |
| • | 01672 | CL | W(TIMECORRC) | 02001 | 16030 | 02055 | TIME CORRECTION PROGRAM |
| • | 01673 | ENT | A*W(AZIMSH+5) | 02002 | 11030 | 00475 | |
| • | 01674 | SUB | A*W(AZIMSH+2) | 02003 | 21030 | 00472 | |
| • | 01675 | ADD | A*W(ELEVSH+5) | 02004 | 20030 | 00503 | |
| • | 01676 | SUB | A*W(ELEVSH+2) | 02005 | 21030 | 00500 | A2 - A-1 + E2 - E-1 |
| • | 01677 | STR | A*W(JUNK) | 02006 | 15030 | 00577 | |
| • | 01700 | ENT | A*W(LOCSCBIAS) | 02007 | 11030 | 01227 | |
| • | 01701 | ADD | A*W(LOCSCBIAS) | 02010 | 20030 | 01225 | |
| • | 01702 | CL | Q | 02011 | 10000 | 00000 | |
| • | 01703 | RSH | AQ*90 | 02012 | 03000 | 00011 | B21 |
| • | 01704 | DIV | W(JUNK) | 02013 | 23030 | 00577 | TIME IN 6-SECOND INTERVALS B21 |
| • | 01705 | LSH | AQ*300 | 02014 | 07000 | 00036 | |
| • | 01706 | STR | A*W(JUNK) | 02015 | 15030 | 00577 | |
| • | 01707 | RSH | AQ*80 | 02016 | 03000 | 00010 | |
| • | 01710 | DIV | W(S+1)*SKIP | 02017 | 23130 | 02020 | |
| • | 01711 | 341000000 | | 02020 | 34100 | 00000 | 14400B15 NO OF 6 SEC IN A DAY |
| • | 01712 | STR | Q*W(TIMECORR) | 02021 | 14030 | 63107 | TIME CORRECTION TO MCP |
| • | 01713 | ENT | Q*W(AZIMSH+2) | 02022 | 10030 | 00472 | |
| • | 01714 | SUB | Q*W(AZIMSH+5) | 02023 | 27030 | 00475 | |
| • | 01715 | MUL | W(JUNK) | 02024 | 22030 | 00577 | |
| • | 01716 | RSH | AQ*210 | 02025 | 03000 | 00025 | |
| • | 01717 | RPT | 6*ADV | 02026 | 70100 | 00006 | |
| • | 01720 | RPL | Y-Q*W(AZIMSH) | 02027 | 35030 | 00470 | |
| • | 01721 | RPL | Y+Q*W(LOCSCBIAS) | 02030 | 34030 | 01225 | |
| • | 01722 | ENT | Q*W(ELEVSH+2) | 02031 | 10030 | 00500 | |
| • | 01723 | SUB | Q*W(ELEVSH+5) | 02032 | 27030 | 00503 | |
| • | 01724 | MUL | W(JUNK) | 02033 | 22030 | 00577 | |
| • | 01725 | RSH | AQ*210 | 02034 | 03000 | 00025 | |
| • | 01726 | RPT | 6*ADV | 02035 | 70100 | 00006 | |
| • | 01727 | RPL | Y-Q*W(ELEVSH) | 02036 | 35030 | 00476 | |
| • | 01730 | RPL | Y+Q*W(LOCSCBIAS) | 02037 | 34030 | 01227 | |
| • | 01731 | JP | L(ACQUIRUN) | 02040 | 61010 | 00360 | PRINT ACQUIRED MESSAGE |
| • | 01732 | RJP | U(PRL0G) | 02041 | 65020 | 63423 | |
| • | 01733 | 3 | ACQUIMSG1 | 02042 | 00003 | 02046 | |
| • | 01734 | 1 | -280 | 02043 | 00001 | 77743 | |
| • | 01735 | NO-0P | | 02044 | 12000 | 00000 | |
| • | 01736 | JP | NEWMEAN | 02045 | 61000 | 01553 | |

| | | | | | | | | |
|---|-------|------------|------------|----------------------|-------|-------|-------|--------------------------------|
| • | 01737 | ACQUIMS61 | FD | 0*TARGET ACQUIRED | 02046 | 31062 | 71412 | |
| • | 01740 | ACQY | 0 | | 02047 | 31050 | 61026 | |
| • | 01741 | ACQYSQ | 0 | | 02050 | 32162 | 71211 | Y R27 |
| • | 01742 | ACQYCUBE | 0 | | 02051 | 00000 | 00000 | YY B27 |
| • | 01743 | THIRD | 0 | | 02052 | 00000 | 00000 | YYY B27 |
| • | 01744 | TIMECORRC | 0 | 2525252461 | 02053 | 00000 | 00000 | .3333333B30 1/3 B30 |
| • | 01745 | ACGA | 0 | RESERVE 4 | 02054 | 25252 | 52461 | |
| • | 01746 | ACGA1 | 1000000000 | RESERVE 164D | 02055 | 00000 | 00000 | INTERPOLATION COEFFICIENTS B27 |
| • | 01747 | RP2TABLE1 | 0 | RESERVE 164D | 02056 | 00000 | 00000 | RP2 BUFFER TABLE N01 GOES WITH |
| • | 01750 | RP2TABLE2 | 0 | RESERVE 164D | 02062 | 10000 | 00000 | RP2 BUFFER TABLE N01 GOES WITH |
| • | 01751 | RP2COUNT | 0 | 0 | 02063 | 00000 | 00000 | RP2 BUFFER TABLE N02 |
| • | 01752 | JUNKY | 0 | RESERVE 1 | 02327 | 00000 | 00000 | RP2 BUFFER FABLE N02 |
| • | 01753 | RP2CHANNEL | 0 | 0 | 02573 | 00000 | 00000 | RP2 COUNT U FOR TABLE1 L FOR |
| • | 01754 | RP2TABLEID | 0 | 0 | 02574 | 00000 | 00000 | TABLE2 |
| • | 01755 | RP2INTERPT | ENTRY | RP2TABLE1*RP2TABLE2 | 02575 | 00000 | 00000 | TEMPORARY STORAGE |
| • | 01756 | | STR | B6*U(RP2INTERPT) | 02576 | 02063 | 02327 | |
| • | 01757 | | STR | G*W(JUNKG) | 02577 | 61000 | 00000 | |
| • | 01760 | | STR | A*W(JUNKY) | 02600 | 16820 | 02577 | SAVE A AND B6 |
| • | 01761 | | PUT | -0*W(TRACKINDIC) | 02601 | 14030 | 02647 | |
| • | 01762 | | ENT | Q*U(113) | 02602 | 15030 | 02574 | |
| • | 01763 | | SUB | G*AZIMIN+4990*QZERO | 02603 | 10040 | 77777 | |
| • | 01764 | | ENT | A*L(RP2COUNT)*SKIP | 02604 | 14030 | 63026 | |
| • | 01765 | | ENT | A*U(RP2COUNT) | 02605 | 10020 | 00113 | |
| • | 01766 | | SUB | A*164D*ANEG | 02606 | 27400 | 75763 | |
| • | 01767 | | ENT | A*4*SKIP | 02607 | 11110 | 02573 | |
| • | 01770 | | ADD | A*168D | 02610 | 11020 | 02573 | |
| • | 01771 | | ADD | Q*0*QZERO | 02611 | 21700 | 00244 | |
| • | 01772 | | STR | A*L(RP2COUNT)*SKIP | 02612 | 11100 | 00004 | |
| • | 01773 | | STR | A*U(RP2COUNT)*SKIP | 02613 | 20000 | 00250 | |
| • | 01774 | | ADD | A*L(RP2TABLEID)*SKIP | 02614 | 26400 | 00000 | |
| • | 01775 | | ADD | A*U(RP2TABLEID)*SKIP | 02615 | 15110 | 02573 | |
| • | 01776 | | SUB | A*4 | 02616 | 15120 | 02573 | |
| • | 01777 | | ENT | B6*A | 02617 | 20110 | 02576 | |
| • | 02000 | | ENT | A*W(113) | 02620 | 20020 | 02576 | |
| • | 02001 | | STR | A*W(B6) | 02621 | 21000 | 00004 | |
| • | 02002 | | STR | A*W(3+86) | 02622 | 12670 | 00000 | STORE AZIMOUT BCW |
| • | 02003 | | ENT | A*U(RANGEADD) | 02623 | 11030 | 00113 | |
| • | 02004 | | STR | A*L(\$+1) | 02624 | 15036 | 00000 | |
| • | 02005 | | ENT | A*W(0) | 02625 | 15036 | 00003 | STORE RANGE |
| • | 02006 | | STR | A*W(1+86) | 02626 | 11020 | 63445 | |
| • | 02007 | | ENT | A*U(B6) | 02627 | 15010 | 02630 | |
| • | 02010 | | SUB | A*L(B6) | 02630 | 11030 | 00000 | STORE DOPPLER |
| • | 02011 | | ADD | A*U(D0PPADD) | 02631 | 15036 | 00001 | |
| • | 02012 | | SUB | A*5000 | 02632 | 21016 | 00000 | |
| • | 02013 | | STR | A*L(\$+1) | 02633 | 21016 | 00000 | |
| • | 02014 | | ENT | A*W(0) | 02634 | 20020 | 63444 | |
| • | 02015 | | STR | A*W(2+86) | 02635 | 21000 | 00764 | |
| • | 02016 | | ENT | G*W(JUNKG) | 02636 | 15010 | 02637 | |
| • | 02017 | | ENT | A*W(JUNKY) | 02637 | 11030 | 00000 | |
| • | 02020 | | ENT | B6*U(RP2INTERPT) | 02640 | 15036 | 00002 | |
| • | 02021 | | STR | C14*W(RP2CHANNEL) | 02641 | 10030 | 02647 | |
| • | 02022 | WEIGHTTID | RILJP | L(RP2INTERPT) | 02642 | 11030 | 02574 | RESTORE A AND B6 |
| • | 02023 | WEIGHTTID | U-TAG | WEIGHTT1*WEIGHTT2 | 02643 | 12620 | 02577 | |
| • | 02024 | JUNKG | 0 | 0 | 02644 | 17630 | 02575 | |
| • | | | | | 02645 | 60110 | 02577 | ARTIFICIAL WEIGHT TABLE |
| • | | | | | 02646 | 02650 | 02721 | |
| • | | | | | 02647 | 00000 | 00000 | |

| | 02025 | WEIGHTT1 | | 1 | 0 | | 02650 | 00001 | 00000 | ALL RP2 PULSES HAVE EQUAL MAX WEIGHT MAXIMUM VALUE COULD BE 1B15 |
|---|-------|----------|---|---|---|--|-------|-------|-------|---|
| . | 02026 | | 1 | 1 | 0 | | 02651 | 00001 | 00000 | |
| . | 02027 | | 1 | 1 | 0 | | 02652 | 00001 | 00000 | |
| . | 02030 | | 1 | 1 | 0 | | 02653 | 00001 | 00000 | |
| . | 02031 | | 1 | 1 | 0 | | 02654 | 00001 | 00000 | |
| . | 02032 | | 1 | 1 | 0 | | 02655 | 00001 | 00000 | |
| . | 02033 | | 1 | 1 | 0 | | 02656 | 00001 | 00000 | |
| . | 02034 | | 1 | 1 | 0 | | 02657 | 00001 | 00000 | |
| . | 02035 | | 1 | 1 | 0 | | 02660 | 00001 | 00000 | |
| . | 02036 | | 1 | 1 | 0 | | 02661 | 00001 | 00000 | |
| . | 02037 | | 1 | 1 | 0 | | 02662 | 00001 | 00000 | |
| . | 02040 | | 1 | 1 | 0 | | 02663 | 00001 | 00000 | |
| . | 02041 | | 1 | 1 | 0 | | 02664 | 00001 | 00000 | |
| . | 02042 | | 1 | 1 | 0 | | 02665 | 00001 | 00000 | |
| . | 02043 | | 1 | 1 | 0 | | 02666 | 00001 | 00000 | |
| . | 02044 | | 1 | 1 | 0 | | 02667 | 00001 | 00000 | |
| . | 02045 | | 1 | 1 | 0 | | 02670 | 00001 | 00000 | |
| . | 02046 | | 1 | 1 | 0 | | 02671 | 00001 | 00000 | |
| . | 02047 | | 1 | 1 | 0 | | 02672 | 00001 | 00000 | |
| . | 02050 | | 1 | 1 | 0 | | 02673 | 00001 | 00000 | |
| . | 02051 | | 1 | 1 | 0 | | 02674 | 00001 | 00000 | |
| . | 02052 | | 1 | 1 | 0 | | 02675 | 00001 | 00000 | |
| . | 02053 | | 1 | 1 | 0 | | 02676 | 00001 | 00000 | |
| . | 02054 | | 1 | 1 | 0 | | 02677 | 00001 | 00000 | |
| . | 02055 | | 1 | 1 | 0 | | 02700 | 00001 | 00000 | |
| . | 02056 | | 1 | 1 | 0 | | 02701 | 00001 | 00000 | |
| . | 02057 | | 1 | 1 | 0 | | 02702 | 00001 | 00000 | |
| . | 02060 | | 1 | 1 | 0 | | 02703 | 00001 | 00000 | |
| . | 02061 | | 1 | 1 | 0 | | 02704 | 00001 | 00000 | |
| . | 02062 | | 1 | 1 | 0 | | 02705 | 00001 | 00000 | |
| . | 02063 | | 1 | 1 | 0 | | 02706 | 00001 | 00000 | |
| . | 02064 | | 1 | 1 | 0 | | 02707 | 00001 | 00000 | |
| . | 02065 | | 1 | 1 | 0 | | 02710 | 00001 | 00000 | |
| . | 02066 | | 1 | 1 | 0 | | 02711 | 00001 | 00000 | |
| . | 02067 | | 1 | 1 | 0 | | 02712 | 00001 | 00000 | |
| . | 02070 | | 1 | 1 | 0 | | 02713 | 00001 | 00000 | |
| . | 02071 | | 1 | 1 | 0 | | 02714 | 00001 | 00000 | |
| . | 02072 | | 1 | 1 | 0 | | 02715 | 00001 | 00000 | |
| . | 02073 | | 1 | 1 | 0 | | 02716 | 00001 | 00000 | |
| . | 02074 | | 1 | 1 | 0 | | 02717 | 00001 | 00000 | |
| . | 02075 | | 1 | 1 | 0 | | 02720 | 00001 | 00000 | |
| . | 02076 | WEIGHTT2 | 1 | 1 | 0 | | 02721 | 00001 | 00000 | |
| . | 02077 | | 1 | 1 | 0 | | 02722 | 00001 | 00000 | |
| . | 02100 | | 1 | 1 | 0 | | 02723 | 00001 | 00000 | |
| . | 02101 | | 1 | 1 | 0 | | 02724 | 00001 | 00000 | |
| . | 02102 | | 1 | 1 | 0 | | 02725 | 00001 | 00000 | |
| . | 02103 | | 1 | 1 | 0 | | 02726 | 00001 | 00000 | |
| . | 02104 | | 1 | 1 | 0 | | 02727 | 00001 | 00000 | |
| . | 02105 | | 1 | 1 | 0 | | 02730 | 00001 | 00000 | |
| . | 02106 | | 1 | 1 | 0 | | 02731 | 00001 | 00000 | |
| . | 02107 | | 1 | 1 | 0 | | 02732 | 00001 | 00000 | |
| . | 02110 | | 1 | 1 | 0 | | 02733 | 00001 | 00000 | |
| . | 02111 | | 1 | 1 | 0 | | 02734 | 00001 | 00000 | |
| . | 02112 | | 1 | 1 | 0 | | 02735 | 00001 | 00000 | |
| . | 02113 | | 1 | 1 | 0 | | 02736 | 00001 | 00000 | |
| . | 02114 | | 1 | 1 | 0 | | 02737 | 00001 | 00000 | |
| . | 02115 | | 1 | 1 | 0 | | 02740 | 00001 | 00000 | |

| | | | | | | |
|---|-------|---|---|-------|-------|-------|
| . | 02116 | 1 | 0 | 02741 | 00001 | 00000 |
| . | 02117 | 1 | 0 | 02742 | 00001 | 00000 |
| . | 02120 | 1 | 0 | 02743 | 00001 | 00000 |
| . | 02121 | 1 | 0 | 02744 | 00001 | 00000 |
| . | 02122 | 1 | 0 | 02745 | 00001 | 00000 |
| . | 02123 | 1 | 0 | 02746 | 00001 | 00000 |
| . | 02124 | 1 | 0 | 02747 | 00001 | 00000 |
| . | 02125 | 1 | 0 | 02750 | 00001 | 00000 |
| . | 02126 | 1 | 0 | 02751 | 00001 | 00000 |
| . | 02127 | 1 | 0 | 02752 | 00001 | 00000 |
| . | 02130 | 1 | 0 | 02753 | 00001 | 00000 |
| . | 02131 | 1 | 0 | 02754 | 00001 | 00000 |
| . | 02132 | 1 | 0 | 02755 | 00001 | 00000 |
| . | 02133 | 1 | 0 | 02756 | 00001 | 00000 |
| . | 02134 | 1 | 0 | 02757 | 00001 | 00000 |
| . | 02135 | 1 | 0 | 02760 | 00001 | 00000 |
| . | 02136 | 1 | 0 | 02761 | 00001 | 00000 |
| . | 02137 | 1 | 0 | 02762 | 00001 | 00000 |
| . | 02140 | 1 | 0 | 02763 | 00001 | 00000 |
| . | 02141 | 1 | 0 | 02764 | 00001 | 00000 |
| . | 02142 | 1 | 0 | 02765 | 00001 | 00000 |
| . | 02143 | 1 | 0 | 02766 | 00001 | 00000 |
| . | 02144 | 1 | 0 | 02767 | 00001 | 00000 |
| . | 02145 | 1 | 0 | 02770 | 00001 | 00000 |
| . | 02146 | 1 | 0 | 02771 | 00001 | 00000 |
| . | 02147 | 1 | 0 | 02772 | 12000 | 00000 |
| . | | | | 02773 | 04000 | 00000 |
| | | | | 02774 | 77740 | 00000 |
| | | | | 02775 | 77760 | 00000 |

SPURT OUTPUT NO. 112

TEOSTE*10FEB66

| ACQUI | | LABEL | | LOC | | LABEL | | LOC | | LABEL | | LOC | |
|-------|-------------|-------|------------|-------|-------|------------|-------|-------|-------|------------|-------|-------|-------|
| 00000 | ACQUIRE | 00000 | ACQUIINIT | 00002 | 00002 | ATTENTINIT | 00034 | 00002 | 00002 | ATTENTINIT | 00034 | 00002 | 00002 |
| | CHOICE | | DONOTHING | | | STOPACQUI | | | | STOPACQUI | | | |
| | NOINTERR | | ACQUIONOFF | | | QUEST1 | | | | QUEST1 | | | |
| | ANSWER1 | | PROGTABLE | | | QUEST3 | | | | QUEST3 | | | |
| 00070 | QUEST2 | 00120 | ANSWER2 | 00142 | 00074 | HSACQUI | 00105 | 00142 | 00074 | HSACQUI | 00105 | 00142 | 00074 |
| | WFSACQUI6 | | WFSACQUI | | | BACKUPWD | | | | BACKUPWD | | | |
| | SCHCHOICE | | WFSACQUI4 | | | CLBIASES | | | | CLBIASES | | | |
| | TIMECORREC | | TIMECODE | | | QUEST4 | | | | QUEST4 | | | |
| 00231 | ANSWER4 | 00231 | QUEST5 | 00235 | 00205 | ANSWERS | 00246 | 00235 | 00205 | ANSWERS | 00246 | 00235 | 00205 |
| | SETBIASES | | AZENTBIAS | | | ELENTBIAS | | | | ELENTBIAS | | | |
| | TEMPST | | QUEST6 | | | ANSWER6 | | | | ANSWER6 | | | |
| | QUEST7 | | ANSWER7 | | | LOCCHOICE | | | | LOCCHOICE | | | |
| 00336 | WFSACQUI5 | 00336 | LOCSCONLY | 00342 | 00324 | RP2INTRJP | 00343 | 00342 | 00324 | RP2INTRJP | 00343 | 00342 | 00324 |
| | TEST3 | | TEST5 | | | TEST4 | | | | TEST4 | | | |
| | ACQUIRUN | | STARTAZ | | | ENDAZ | | | | ENDAZ | | | |
| | NORP2PULSE | | SIMULATION | | | PUTINCCW | | | | PUTINCCW | | | |
| 00466 | PUTINCW | 00466 | TEST1 | 00444 | 00424 | TEST2 | 00456 | 00444 | 00424 | TEST2 | 00456 | 00444 | 00424 |
| | REV | | MARGIN | | | AZIMSH | | | | AZIMSH | | | |
| | ELEVSH | | SGRT | | | SCANLIN | | | | SCANLIN | | | |
| | SCANACCMNEG | | CROSSCAN | | | ECROSSCAN | | | | ECROSSCAN | | | |
| 00551 | ACROSSCAN | 00551 | DELCRSC | 00552 | 00552 | SCSIN | 00556 | 00552 | 00552 | SCSIN | 00556 | 00552 | 00552 |
| | SCC05 | | CRSCW | | | I | | | | I | | | |
| | N | | SCANPOINT | | | HORIZTEST | | | | HORIZTEST | | | |
| | AZDIFM10 | | AZDIF20 | | | ELDIFM10 | | | | ELDIFM10 | | | |
| 00570 | ELDIF20 | 00570 | ELDIF20SQ | 00571 | 00571 | AZDIF20SQ | 00572 | 00571 | 00571 | AZDIF20SQ | 00572 | 00571 | 00571 |
| | SGRTDEN | | ELPOINT | | | ELPOINT | | | | ELPOINT | | | |
| | SCANMODE | | JUNK | | | FITDENOM | | | | FITDENOM | | | |
| | FITQUAD | | FITLIN | | | SCS | | | | SCS | | | |
| 00603 | SC3 | 00603 | SC4 | 00604 | 00604 | ENDSSC | 00716 | 00604 | 00604 | ENDSSC | 00716 | 00604 | 00604 |
| | SEARCH101 | | ENDSSC1 | | | WIDTHIN | | | | WIDTHIN | | | |
| | LENGTHIN | | BELOWHORIZ | | | SEARCHSCAN | | | | SEARCHSCAN | | | |
| | ENDANGLE | | SC1 | | | SC10 | | | | SC10 | | | |
| 01037 | SC2 | 01037 | AZT0GOWEL | 01051 | 01027 | ENDFIT | 01116 | 01051 | 01027 | ENDFIT | 01116 | 01051 | 01027 |
| | SSCANINIT | | RECIPREV | | | MAXSCACC | | | | MAXSCACC | | | |
| | LENGTH | | WIDTH | | | SCMINEL | | | | SCMINEL | | | |
| | NARBITRARY | | NROUND | | | RP2AVG2A | | | | RP2AVG2A | | | |
| 01204 | RP2AVG8A | 01204 | RP2AVGSA | 01213 | 01213 | RP2AVGLA | 01214 | 01213 | 01213 | RP2AVGLA | 01214 | 01213 | 01213 |
| | RP2CODE2 | | LOCSCK | | | RP2CODE8 | | | | RP2CODE8 | | | |
| | RP2CODES | | GOODLSCNT | | | RP2CODEL | | | | RP2CODEL | | | |
| | RAIUS | | AVGBCW | | | DELRAIUS | | | | DELRAIUS | | | |
| 01224 | MAXRADIUS | 01224 | LOCSCBIAS | 01222 | 01222 | WEIGHTSUM | 01226 | 01222 | 01222 | WEIGHTSUM | 01226 | 01222 | 01222 |
| | LOCSCBIAS | | RP2AVG2E | | | RP2AVG8E | | | | RP2AVG8E | | | |
| | RP2AVGSE | | RP2AVGLE | | | FIVEHUND | | | | FIVEHUND | | | |
| | LOCSCCTABLE | | GETAVG8 | | | AVGAZOCY | | | | AVGAZOCY | | | |
| 01235 | INTERAZCY | 01235 | AVGROUTINE | 01304 | 01261 | AVGL00P | 01320 | 01304 | 01261 | AVGL00P | 01320 | 01261 | 01261 |
| | WFSACQUI11 | | NONOVERLAP | | | WFSACQUI12 | | | | WFSACQUI12 | | | |
| | LOCALSCAN | | INOVERLAP | | | KTABLE | | | | KTABLE | | | |
| | KIS0 | | KIS1 | | | KIS2 | | | | KIS2 | | | |
| 01507 | KIS3 | 01507 | KIS4 | 01511 | 01511 | NEWMEAN | 01526 | 01511 | 01511 | NEWMEAN | 01526 | 01511 | 01511 |
| | INITLOCSC | | LASTTEST | | | FIRSTLOC | | | | FIRSTLOC | | | |
| | CLEARCOUNT | | LEFTSSCRP2 | | | BACKUPSCAN | | | | BACKUPSCAN | | | |
| | NEGI | | POSP05 | | | LOCSCC0MP1 | | | | LOCSCC0MP1 | | | |

| | | | | | |
|-------------|-------|--------------|-------|-------------|-------|
| LOCSCCOMP | 01723 | ACQUIMSG | 02041 | ACQUIMSG1 | 02046 |
| ACQY | 02051 | ACQYSQ | 02052 | ACQYCUBE | 02053 |
| THIRD | 02054 | TIMCORRC | 02055 | ACQA | 02056 |
| ACGAI | 02062 | RP2TABLE1 | 02063 | RP2TABLE2 | 02327 |
| RP2COUNT | 02573 | JUNKY | 02574 | RP2CHANNEL | 02575 |
| RP2TABLEID | 02576 | RP2INTERPT | 02577 | WEIGHTIID | 02646 |
| JUNKO | 02647 | WEIGHTI1 | 02650 | WEIGHTT2 | 02721 |
| AS\$S\$1111 | 02773 | AS\$S\$1112 | 02774 | AS\$S\$1113 | 02775 |
| ID1CELCOR | 63000 | ID2CELCOR | 63001 | RA | 63002 |
| DEC | 63003 | SRA | 63004 | SECC | 63005 |
| RADIUS | 63006 | RADOT | 63007 | DECOOT | 63010 |
| RADIUSDOT | 63011 | SIDERTIME | 63012 | VIZRA1 | 63013 |
| VIZDEC1 | 63014 | VIZRA2 | 63015 | VIZDEC2 | 63016 |
| TWSECCOP | 63017 | PLTAZIM\$ | 63020 | PLOTELEV\$ | 63021 |
| AZTRACKERR | 63022 | ELTRACKERR | 63023 | MODESWITCH | 63024 |
| AUTOSWITCH | 63025 | TRACKINDIC | 63026 | AZIMERROR\$ | 63027 |
| ELEVERROR\$ | 63030 | ID1RADCOR | 63050 | ID2RADCOR | 63051 |
| RANGE | 63052 | AZIM | 63053 | ELEV | 63054 |
| SAZIM | 63055 | SELEV | 63056 | CRANGE | 63057 |
| CAZIM | 63060 | CELEV | 63061 | RANGEDOT | 63062 |
| TRUERANGE | 63063 | SINORIENT | 63064 | COSORIENT | 63065 |
| SINAZEL | 63066 | COSAZEL | 63070 | ACGAZIM | 63071 |
| ACGELEV | 63075 | FRAMESIZE | 63101 | RADIOMETER | 63102 |
| TIMEMODE | 63103 | FIRSTELEV | 63104 | ASTRORA | 63105 |
| ASTRODEC | 63106 | TIMECORR | 63107 | KYBRDLEVEL | 63110 |
| TTYSTATUS | 63111 | RECORDSIZE | 63112 | CELBODY | 63113 |
| AZDIFS | 63120 | ELDIFS | 63121 | RDIFS | 63122 |
| ROTDIFS | 63123 | SLAVEOPTS | 63124 | SLAVEMODES | 63125 |
| SLAVE | 63126 | IDTIME | 63130 | ID2TIME | 63131 |
| TRUETIME | 63132 | CELTIME | 63133 | SCELTIME | 63134 |
| CONVERTIME | 63135 | SRADTIME | 63136 | HOURMINUTE | 63137 |
| SECONDS | 63140 | DSECONDS | 63141 | ACTUALTIME | 63142 |
| ESTSHIFTED | 63143 | GMTSHIFTED | 63144 | ACTUALTIME | 63145 |
| BLASTOFF | 63146 | YEARMONTH | 63147 | DAY | 63150 |
| HOUREG | 63151 | MINREG | 63152 | FIRSTTHRU | 63153 |
| DUMSECTTG | 63154 | RECRD SWITCH | 63155 | RELEASESW | 63156 |
| RADINDIC | 63157 | PRINRECSW | 63160 | REFRACIND\$ | 63161 |
| AZELIND\$ | 63162 | ID1RECRD | 63210 | ID2RECRD | 63211 |
| RECFILE | 63212 | ID1SYSPAR | 63310 | ID2SYSPAR | 63311 |
| RADARMODE | 63312 | SYSTAT1 | 63313 | SYSTAT2 | 63314 |
| SYSTATD | 63315 | DELTAEE | 63316 | FREQUENCY | 63317 |
| LONGITUDE | 63320 | GEODETLAT | 63321 | GECCENLAT | 63322 |
| EQUATOR | 63323 | POLE | 63324 | AZIMOVER | 63325 |
| HEIGHT | 63326 | YRTRAN | 63327 | ZRTRAN | 63330 |
| SKIP | 63331 | MSFREQ | 63332 | WFFREQ | 63333 |
| MAINSWITCH | 63334 | VELOFLIGHT | 63335 | LSPERAU | 63336 |
| FLATTENING | 63337 | NMPERAU | 63340 | AUPEREGUAT | 63341 |
| KMPERNM | 63342 | KYBRDSPEC1 | 63344 | KYBRDSPEC2 | 63345 |
| KYBRDSPEC3 | 63346 | KYBRDSPEC4 | 63347 | EXPNAME | 63350 |
| IDIENTPNT | 63410 | ID2ENTPNT | 63411 | MCPGM | 63412 |
| INTER | 63413 | COCN | 63414 | RECRD | 63415 |
| ADSCN | 63416 | AESCN | 63417 | CORCT | 63420 |
| DYDMP | 63421 | CHCOR | 63422 | PRLOG | 63423 |
| CELCOMPGM | 63424 | DATANALYZE | 63425 | INTERCOM | 63426 |
| ACQUI | 63427 | RDMPTR | 63430 | CHPAR | 63431 |
| #FORD | 63432 | RDXXX | 63433 | PLANP | 63434 |
| TIMPE | 63435 | PL0TP | 63436 | AUTOT | 63437 |
| ID1RAD10 | 63440 | ID2RAD10 | 63441 | AZIMADD | 63442 |
| ELEVADD | 63443 | DOPPAD | 63444 | RANGEADD | 63445 |

| | | | | | |
|------------|-------|------------|-------|-------------|-------|
| INAZIMADD | 63446 | INELEVADD | 63447 | WFADD | 63450 |
| MILLSTNADD | 63451 | SYSKOMREG1 | 63452 | SYSKOMREG2 | 63453 |
| SYSKOMREG3 | 63454 | SYSKOMREG4 | 63455 | SYSKOMREG5 | 63456 |
| SYSKOMREG6 | 63457 | INTERLCKSW | 63460 | PREVIOUSSTM | 63461 |
| BODYSIZE | 63462 | AZELBXSCAN | 63500 | AZMTHSCAN | 63501 |
| ELVTNSCAN | 63502 | RADCBXSCAN | 63503 | RASCTNSCAN | 63504 |
| DECLNSCAN | 63505 | ALNGACRSCN | 63506 | AEBOXLINES | 63507 |
| RDBOXLINES | 63510 | HOLDNOHOLD | 63511 | AZIM0FFSET | 63512 |
| ELEV0FFSET | 63513 | RA0FFSET | 63514 | DEC0FFSET | 63515 |
| CRSS0FFSET | 63516 | ALNG0FFSET | 63517 | TIME0HOLD | 63520 |
| PERI0DELEV | 63521 | ARC0FELEV | 63522 | PERI0DAZIM | 63523 |
| ARC0FAZIM | 63524 | PERI0DEEC | 63525 | ARC0FDEC | 63526 |
| PERI0DRA | 63527 | ARC0FRA | 63530 | RADEC0TIME | 63531 |
| AZEL0TIME | 63532 | RADI0RA | 63540 | RADI0DEC | 63541 |
| SYNCTIMING | 63542 | ID3RADI0 | 63776 | ID4RADI0 | 63777 |
| AZIM0UT | 64000 | ID5RADI0 | 64776 | ID6RADI0 | 64777 |
| ELEV0UT | 65000 | ID7RADI0 | 65776 | ID8RADI0 | 65777 |
| D0PP0UT | 66000 | ID9RADI0 | 66776 | ID10RADI0 | 66777 |
| RECAZIM | 67000 | ID11RADI0 | 67776 | ID12RADI0 | 67777 |
| RECELEV | 70000 | ID13RADI0 | 70775 | ID14RADI0 | 70776 |
| RANGE0UT | 70777 | MCPP0LLER | 71000 | ID15RADI0 | 71776 |
| ID16RADI0 | 71777 | INTERAZIM | 72000 | ID17RADI0 | 72776 |
| ID18RADI0 | 72777 | INTERELEV | 73000 | ID19RADI0 | 73776 |
| ID20RADI0 | 73777 | INTERD0PP | 74000 | ID21RADI0 | 74776 |
| ID22RADI0 | 74777 | AZIMIN | 75000 | ID23RADI0 | 75776 |
| ID24RADI0 | 75777 | ELEVIN | 76000 | ID25RADI0 | 76775 |
| ID26RADI0 | 76776 | INTERRANGE | 76777 | ID1SYSENT | 77576 |
| ID27RADI0 | 77577 | SYSENTRIES | 77600 | ID1SYSNAM | 77676 |
| ID28RADI0 | 77677 | SYSNAMES | 77700 | | |

SPURT OUTPUT NO. 111

TEOSTE*10FEB66

ACQUI

| LABEL | LOC | LABEL | LOC | LABEL | LOC | LABEL | LOC |
|---------------|-------|---------------|-------|---------------|-------|-------|-----|
| A\$S\$S\$1111 | 02773 | A\$S\$S\$1112 | 02774 | A\$S\$S\$1113 | 02775 | | |
| ACGA | 02056 | ACGA1 | 02062 | ACGAZIM | 63071 | | |
| ACGEV | 63075 | ACQAI | 63427 | ACQUIONOFF | 00057 | | |
| ACQUINIT | 00002 | ACQUIMSG | 02041 | ACQUIMSG1 | 02046 | | |
| ACQUIRE | 00000 | ACQIRUN | 00360 | ACQY | 02051 | | |
| ACGYCUBE | 02053 | ACQYSQ | 02052 | ACROSSCAN | 00554 | | |
| ACTUALTIME | 63142 | ADSCN | 63416 | AEROX LINES | 63507 | | |
| AESCN | 63417 | ALNGOFFSET | 63517 | ALNGACRSCN | 63506 | | |
| ANSWER1 | 00070 | ANSWER2 | 00142 | ANSWER4 | 00231 | | |
| ANSWERS | 00246 | ANSWER6 | 00306 | ANSWER7 | 00324 | | |
| ARCOFAZIM | 63524 | ARCOFDEC | 63526 | ARCOFELEV | 63522 | | |
| ARCOFRA | 63530 | ASTRODEC | 63106 | ASTRORA | 63105 | | |
| ATTENTINIT | 00034 | AUPEREGUAT | 63341 | AUTOSWITCH | 63025 | | |
| AUTO1 | 63437 | AVGAZDCY | 01273 | AVGBCW | 01222 | | |
| AVGL00P | 01320 | AVGROUTINE | 01304 | AZDIF20 | 00566 | | |
| AZDIF20SQ | 00572 | AZDIFM10 | 00565 | AZDIFS | 63120 | | |
| AZELOTIME | 63532 | AZELBXSCAN | 63500 | AZELIND\$ | 63162 | | |
| AZENTBIAS | 00272 | AZIM | 63053 | AZIMOFFSET | 63512 | | |
| AZIMOUT | 64000 | AZIMOVER | 63325 | AZIMADD | 63442 | | |
| AZIMERROR\$ | 63027 | AZIMIN | 75000 | AZIMSH | 00470 | | |
| AZMTHSCAN | 63501 | AZPOINT | 00575 | AZT0G0WEL | 01051 | | |
| AZTRACKERR | 63022 | BODYSIZE | 63462 | BACKUPSCAN | 01633 | | |
| BACKUPWD | 00162 | BELOWHORIZ | 00747 | BLASTOFF | 63146 | | |
| COCN | 63414 | CONVERTIME | 63135 | CORCT | 63420 | | |
| COSORIENT | 63065 | COSAZEL | 63070 | CAZIM | 63060 | | |
| CELBODY | 63113 | CELCOMPGM | 63424 | CELEV | 63061 | | |
| CELTIME | 63133 | CHOICE | 00040 | CHCOR | 63422 | | |
| CHPAR | 63431 | CLBIASES | 00210 | CLEARCOUNT | 01620 | | |
| CROSSCAN | 00552 | CRANGE | 63057 | CRSCW | 00560 | | |
| CRSSOFFSET | 63516 | DONOTHING | 00041 | DOPPOUT | 66000 | | |
| DORPAD | 63444 | DATANALYZE | 63425 | DAY | 63150 | | |
| DEC | 63003 | DECOFFSET | 63515 | DECOOT | 63010 | | |
| DECLINSCAN | 63505 | DELCRSC | 00555 | DELRAIUS | 01223 | | |
| DELTATEE | 63316 | DSECONDS | 63141 | DUMSECTTG | 63154 | | |
| DYOMP | 63421 | ECROSSCAN | 00553 | ELDIF20 | 00570 | | |
| ELDIF20SQ | 00571 | ELDIFM10 | 00567 | ELDIFS | 63121 | | |
| ELENTBIAS | 00273 | ELEV | 63054 | ELEV0FFSET | 63513 | | |
| ELEVOUT | 65000 | ELEVADD | 63443 | ELEVEROR\$ | 63030 | | |
| ELEVIN | 76000 | ELEVSH | 00476 | ELPOINT | 00574 | | |
| ELTRACKERR | 63023 | ELVTNSCAN | 63502 | ENDANGLE | 01022 | | |
| ENDAZ | 00403 | ENDFIT | 01116 | ENDSC | 00716 | | |
| ENDSSC1 | 00733 | EQUATOR | 63323 | ESTSHIFTED | 63143 | | |
| EXPNAME | 63350 | FIRSTELEV | 63104 | FIRSTTHRU | 63153 | | |
| FIRSTLOC | 01612 | FITDENOM | 00602 | FITLIN | 00604 | | |
| FITQUAD | 00603 | FIVEHUND | 01234 | FLATTENING | 63337 | | |
| FRAMESIZE | 63101 | FREQUENCY | 63317 | GOODLSCNT | 01217 | | |
| GEOCENLAT | 63322 | GEODETLAT | 63321 | GETAVG8 | 01261 | | |
| GMTMODU24 | 63145 | GMTSHIFTED | 63144 | HOLDNONHOLD | 63511 | | |
| HORIZTEST | 00564 | HOURMINUTE | 63137 | HOURREG | 63151 | | |
| HEIGHT | 63326 | HSACQUI | 00146 | I | 00561 | | |
| ID10RAD10 | 66777 | ID11RAD10 | 67776 | ID12RAD10 | 67777 | | |
| ID13RAD10 | 70775 | ID14RAD10 | 70776 | ID15RAD10 | 71776 | | |

| | | | | | |
|------------|-------|--------------|-------|--------------|-------|
| ID16RADIO | 71777 | ID17RADIO | 72776 | ID18RADIO | 72777 |
| ID19RADIO | 73776 | ID1CELCOR | 63000 | ID1ENTPNT | 63410 |
| ID1RADCOR | 63050 | ID1RADIO | 63440 | ID1RECRD | 63210 |
| ID1SYSENT | 77576 | ID1SYSNAM | 77676 | ID1SYSPAR | 63310 |
| ID1TIME | 63130 | ID20RADIO | 73777 | ID21RADIO | 74776 |
| ID22RADIO | 74777 | ID23RADIO | 75776 | ID24RADIO | 75777 |
| ID25RADIO | 76775 | ID26RADIO | 76776 | ID2CELCOR | 63001 |
| ID2ENTPNT | 63411 | ID2RADCOR | 63051 | ID2RADIO | 63441 |
| ID2RECRD | 63211 | ID2SYSENT | 77577 | ID2SYSNAM | 77677 |
| ID2SYSPAR | 63311 | ID2TIME | 63131 | ID3RADIO | 63776 |
| ID4RADIO | 63777 | ID5RADIO | 64776 | ID6RADIO | 64777 |
| ID7RADIO | 65776 | ID8RADIO | 65777 | ID9RADIO | 66776 |
| INOVERLAP | 01475 | INAZIMADD | 63446 | INELEVADD | 63447 |
| INITLOCSC | 01563 | INTER | 63413 | INTERAZCY | 01277 |
| INTERAZIM | 72000 | INTERCOM | 63426 | INTERDOPP | 74000 |
| INTERELEV | 73000 | INTERLCKSW | 63460 | INTERRANGE | 76777 |
| JUNK | 00577 | JUNKG | 02647 | JUNKY | 02574 |
| KIS0 | 01507 | KIS1 | 01511 | KIS2 | 01526 |
| KIS3 | 01530 | KIS4 | 01535 | KMPERNM | 63342 |
| KTABLE | 01502 | KYBRDLEVEL | 63110 | KYBRDSPEC1 | 63344 |
| KYBRDSPEC2 | 63345 | KYBRDSPEC3 | 63346 | KYBRDSPEC4 | 63347 |
| LOCALSCAN | 01473 | LOCCHOICE | 00330 | LOCSCONLY | 00342 |
| LOCSCABIAS | 01225 | LOCSCCOMP | 01723 | LOCSCCOMP1 | 01720 |
| LOCSCBIAS | 01227 | LOCSCCK | 01215 | LOCSCTABLE | 01235 |
| LONGITUDE | 63320 | LASTEST | 01572 | LEFTSSCRP2 | 01622 |
| LENGTH | 01204 | LENGTHIN | 00745 | LSPERAU | 63336 |
| MODESWITCH | 63024 | MAINSWITCH | 63334 | MARGIN | 00467 |
| MAXRADIUS | 01224 | MAXSCACC | 01203 | MCPFILLER | 71000 |
| MCPGM | 63412 | MILLSTNADD | 63451 | MINREG | 63152 |
| MSFREQ | 63332 | N | 00562 | NOINTERR | 00052 |
| NONOVERLAP | 01441 | NORP2PULSE | 00421 | NARBITRARY | 01207 |
| NEG1 | 01643 | NEWMEAN | 01553 | NMPERAU | 63340 |
| NROUND | 01210 | POLE | 63324 | POSPOS | 01672 |
| PERIODAZIM | 63523 | PERIODDEC | 63525 | PERIODLEVEL | 63521 |
| PERIODRA | 63527 | PL0TAZIM\$\$ | 63020 | PL0TELEV\$\$ | 63021 |
| PL0TP | 63436 | PLANP | 63434 | PROGTABLE | 00074 |
| PREVIOUSTM | 63461 | PRINRECSW | 63160 | PRL0G | 63423 |
| PUTINCCW | 00427 | PUTINCW | 00435 | QUEST1 | 00060 |
| QUEST2 | 00120 | QUEST3 | 00105 | QUEST4 | 00220 |
| QUEST5 | 00235 | QUEST6 | 00275 | QUEST7 | 00312 |
| RA | 63002 | RAOFFSET | 63514 | RAD0T | 63007 |
| RADARMODE | 63312 | RADCBXSCAN | 63503 | RADECOTIME | 63531 |
| RADIODEC | 63541 | RADIOMETER | 63102 | RADIORA | 63540 |
| RADINDIC | 63157 | RADIUS | 63006 | RADIUSD0T | 63011 |
| RAIUS | 01221 | RANGE | 63052 | RANGEOUT | 70777 |
| RANGEADD | 63445 | RANGED0T | 63062 | RASCTNSCAN | 63504 |
| R00DIFS | 63123 | RDBOXLINES | 63510 | RDIFS | 63122 |
| RD0MTR | 63450 | RDXXX | 63433 | RECORDSIZE | 63112 |
| RECACIZM | 67000 | RECELEV | 70000 | RECFILE | 63212 |
| RECIPREV | 01202 | RECRD | 63415 | RECRD0SWTCH | 63155 |
| REFRACINDS | 63161 | RELEASESW | 63156 | REV | 00466 |
| RP2AVG2A | 01211 | RP2AVG2E | 01230 | RP2AVG8A | 01212 |
| RP2AVG8E | 01231 | RP2AVGLA | 01214 | RP2AVGLE | 01233 |
| RP2AVGSA | 01213 | RP2AVGSE | 01232 | RP2C0DE2 | 01215 |
| RP2C0DE8 | 01216 | RP2C0DEL | 01220 | RP2C0DES | 01217 |
| RP2C0UNT | 02573 | RP2CHANNEL | 02575 | RP2INTERPT | 02577 |
| RP2INTRJP | 00343 | RP2TABLE1 | 02063 | RP2TABLE2 | 02327 |
| RP2TABLEID | 02576 | SAZIM | 63055 | SC1 | 01027 |
| SC10 | 01036 | SC2 | 01037 | SC3 | 00660 |

| | | | | | |
|------------|-------|------------|-------|------------|-------|
| SC4 | 00672 | SC5 | 00605 | SCANACCN | 00551 |
| SCANLIN | 00550 | SCANMODE | 00576 | SCANPOINT | 00563 |
| SCC05 | 00557 | SCELTIME | 63134 | SCHCHOICE | 00163 |
| SCMINEL | 01206 | SCSIN | 00556 | SOEC | 63005 |
| SEARCH101 | 00726 | SEARCHSCAN | 00761 | SECONDS | 63140 |
| SELEV | 63056 | SEBIASES | 00252 | SIDERTIME | 63012 |
| SIMULATION | 00424 | SINORIENT | 63064 | SINAZEL | 63066 |
| SKIP | 63331 | SLAVE | 63126 | SLAVEOPTS | 63124 |
| SLAVEMODES | 63125 | SLRT | 00504 | SQRTDEN | 00573 |
| SRA | 63004 | SRADTIME | 63136 | SSCANINIT | 01134 |
| STOPACQUI | 00042 | STARTAZ | 00370 | SYNCTIMING | 63542 |
| SYSOMREG1 | 63452 | SYSOMREG2 | 63453 | SYSOMREG3 | 63454 |
| SYSOMREG4 | 63455 | SYSOMREG5 | 63456 | SYSOMREG6 | 63457 |
| SYSENTRIES | 77600 | SYSNAMES | 77700 | SYSSTAT1 | 63313 |
| SYSSTAT2 | 63314 | SYSSTATD | 63315 | TEMPST | 00274 |
| TEST1 | 00444 | TEST2 | 00456 | TEST3 | 00344 |
| TEST4 | 00357 | TEST5 | 00351 | THIRD | 02054 |
| TIMECODE | 00217 | TIMECORR | 63107 | TIMECORRC | 02055 |
| TIMECORREC | 00214 | TIMEMODE | 63103 | TIMEP | 63435 |
| TIMEOTHOLD | 63520 | TRACKINDIC | 63026 | TRUERANGE | 63063 |
| TRUE TIME | 63132 | TTYSTATUS | 63111 | TWOSECDOP | 63017 |
| VELOFLIGHT | 63335 | VIZDEC1 | 63014 | VIZDEC2 | 63016 |
| VIZRA1 | 63013 | VIZRA2 | 63015 | WEIGHTSUM | 01226 |
| WEIGHTT1 | 02650 | WEIGHTT2 | 02721 | WEIGHTTID | 02646 |
| WFORD | 63432 | WFACQUI | 00156 | WFADD | 63450 |
| WFFREQ | 63333 | WFHSACQUI1 | 01432 | WFHSACQUI2 | 01445 |
| WFHSACQUI4 | 00205 | WFHSACQUI5 | 00336 | WFHSACQUI6 | 00151 |
| WIDTH | 01205 | WIDTHIN | 00744 | YEARMONTH | 63147 |
| YRTRAN | 63327 | ZRTRAN | 63330 | | |

DISTRIBUTION LIST

G. P. Dinneen
H. G. Weiss
S. H. Dodd

Group 31

J. S. Arthur
J. R. Burdette
C. A. Clark
P. Crowther
C. T. Frerichs
R. F. Gagne
G. M. Hyde
R. P. Ingalls
M. L. Meeks
J. E. Moriello
V. C. Pineo
W. Rutkowski
P. B. Sebring
M. L. Stone
R. R. Silva

Group 62

G. Blustein
W. R. Crowther
A. F. Dockrey
J. D. Drinan
P. R. Drouilhet

M. R. Goldberg
D. M. Hafford
D. H. Hamilton
F. E. Heart
D. A. Hunt
L. R. Isenberg
I. L. Lebow
A. A. Mathiasen
F. Nagy
B. E. Nichols
S. B. Russell
R. J. Saliga
P. D. Smith
P. Stylos
R. Teoste
D. C. Walden
Group 62 Files

Group 76

A. O. Kuhnel

Charles W. Adams Associates, Inc.

J. T. Gilmore
142 Great Road
Bedford, Mass.

| DOCUMENT CONTROL DATA - R&D | | |
|---|---|--|
| (Security classification of title, body of abstract and indexing annotation must be entered when the overall report is classified) | | |
| 1. ORIGINATING ACTIVITY (Corporate author) Lincoln Laboratory, M. I. T. | | 2a. REPORT SECURITY CLASSIFICATION Unclassified |
| | | 2b. GROUP None |
| 3. REPORT TITLE Haystack Pointing System: Satellite Acquisition | | |
| 4. DESCRIPTIVE NOTES (Type of report and inclusive dates) Technical Note | | |
| 5. AUTHOR(S) (Last name, first name, initial) Teoste, Rein | | |
| 6. REPORT DATE 30 March 1966 | 7a. TOTAL NO. OF PAGES 60 | 7b. NO. OF REFS 9 |
| 8a. CONTRACT OR GRANT NO. AF 19 (628)-5167 | 9a. ORIGINATOR'S REPORT NUMBER(S) Technical Note 1966-8 | |
| b. PROJECT NO. | 9b. OTHER REPORT NO(S) (Any other numbers that may be assigned this report) | |
| c. 649L | ESD-TDR-66-158 | |
| d. | | |
| 10. AVAILABILITY/LIMITATION NOTICES Distribution of this document is unlimited. | | |
| 11. SUPPLEMENTARY NOTES None | 12. SPONSORING MILITARY ACTIVITY Air Force Systems Command, USAF | |
| 13. ABSTRACT Haystack Pointing System consists of hardware and software which points the Haystack 120-foot X-band antenna dish with great accuracies. The Satellite Acquisition program, described in this report, generates acquisition scans and searches for target returns. Once the target has been sighted, the program tracks the target by conical scanning. After acquisition, time correction can be made in the orbit computations. | | |
| 14. KEY WORDS Haystack antenna pointing system satellite acquisitions computer programs | | |